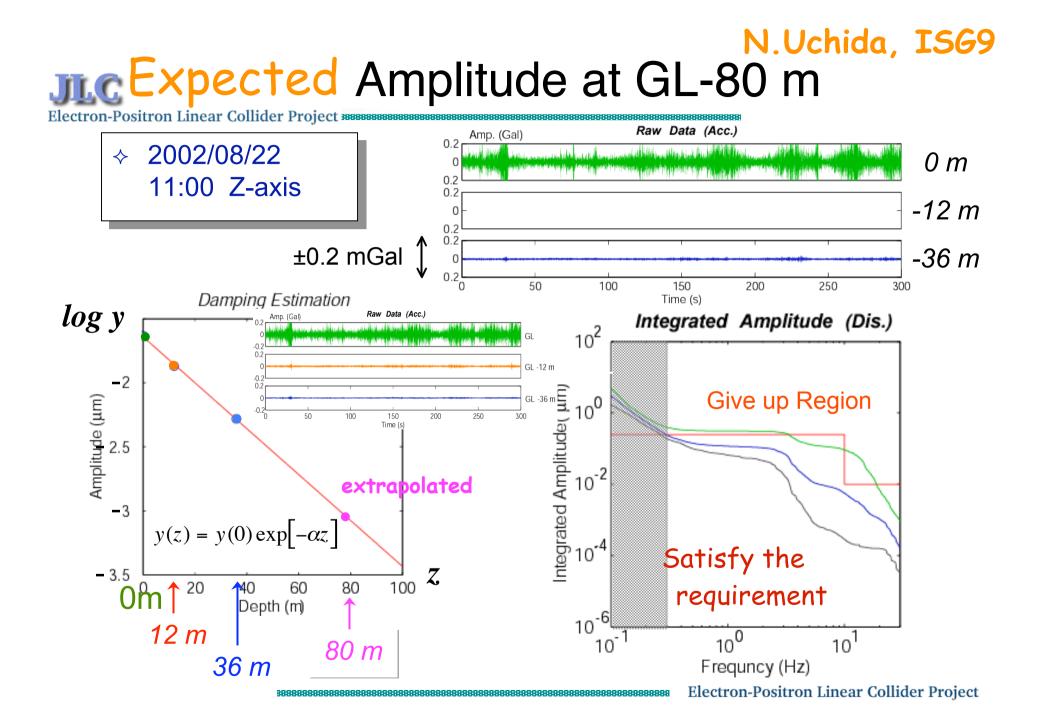
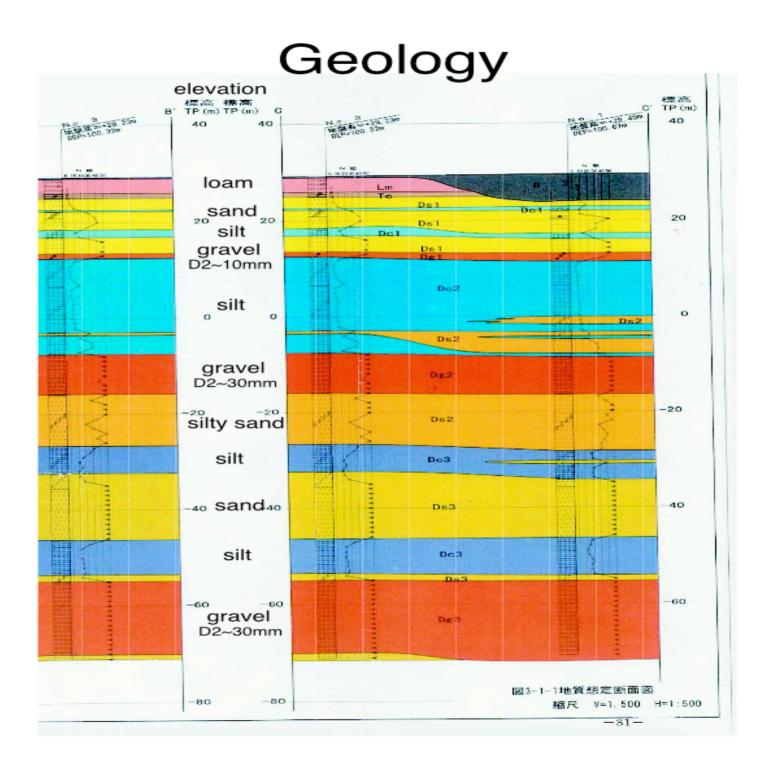
# Preliminary Results of KEK-GM Measurement

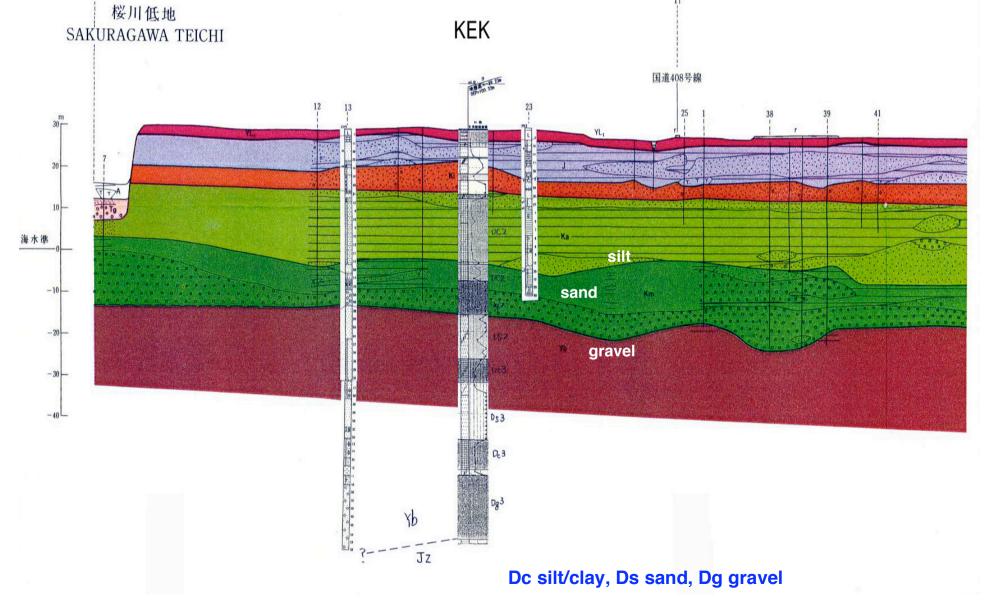
T.Tauchi, K.Fujii, T.Matsuda, H.Yamaoka, N,Uchida, 2003.5.8

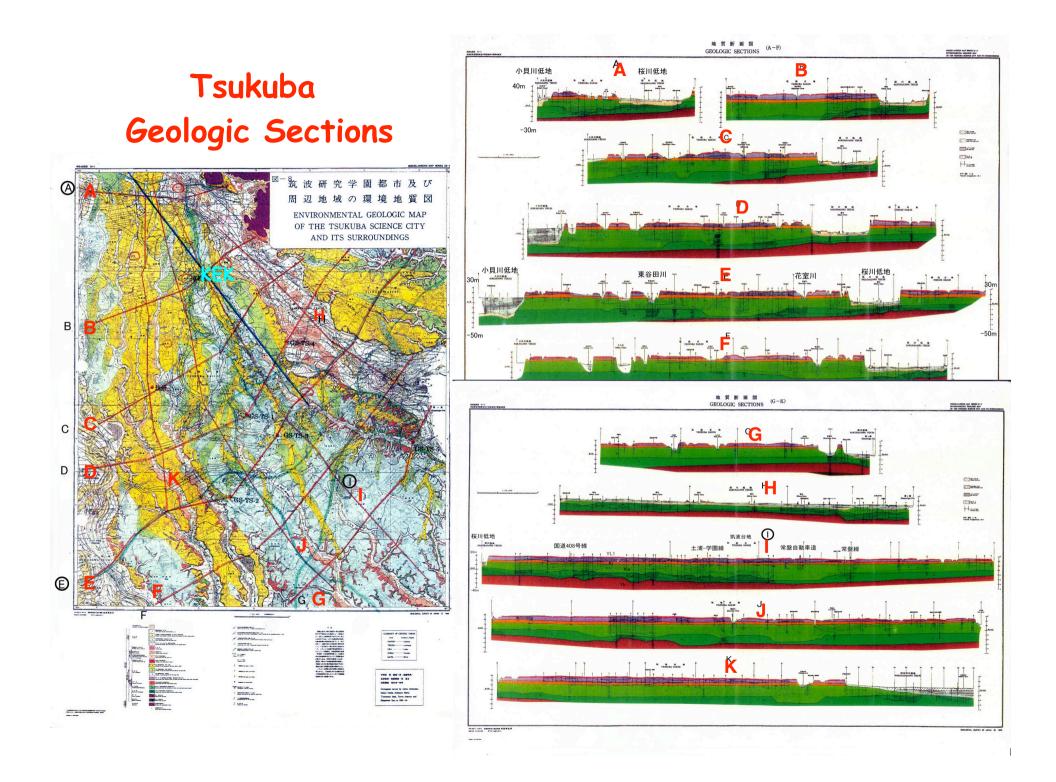
# Ground Motion Measurement at KEK in 2003.1 ~ 3.31 2 sensors (CMG40T) GM measurements 2001 3 80m sand or glass beads 2002 measurement

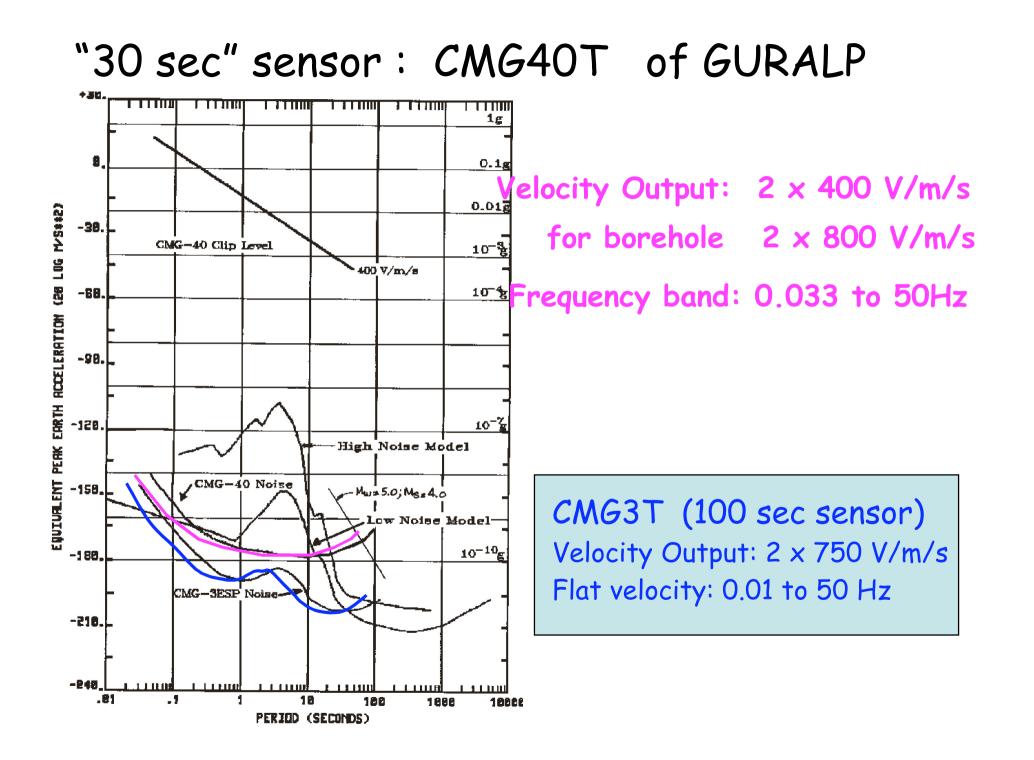






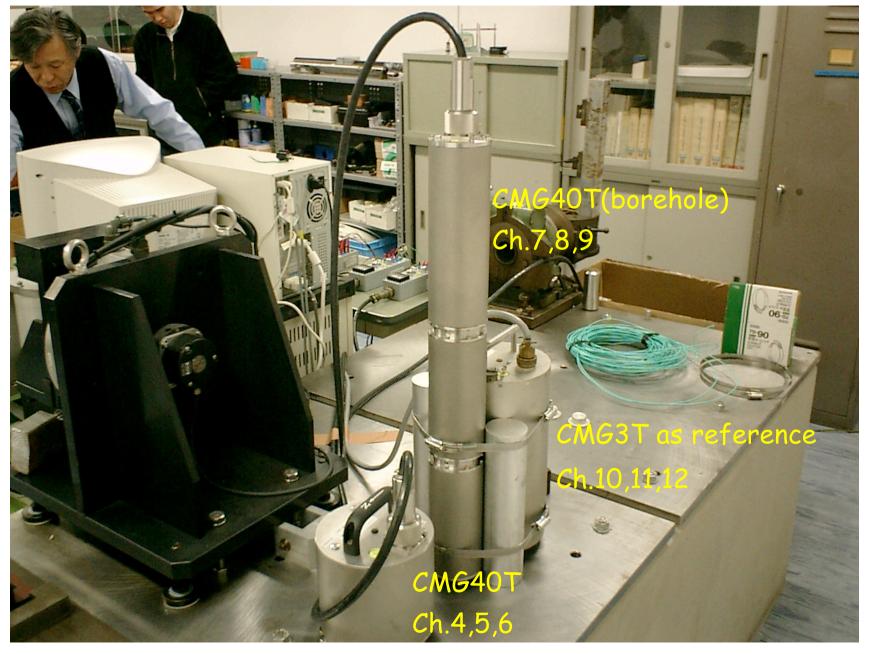






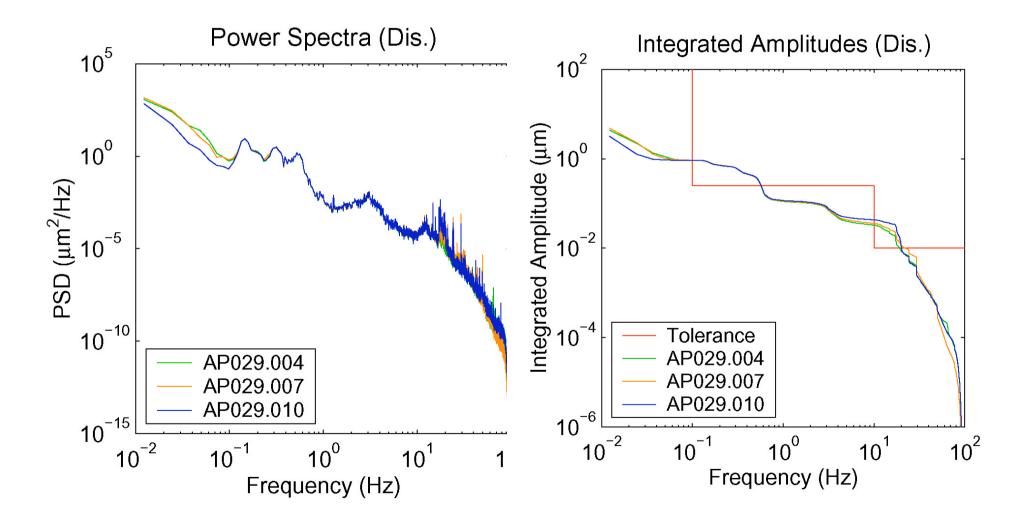
#### Huddle Test

2003.3.10

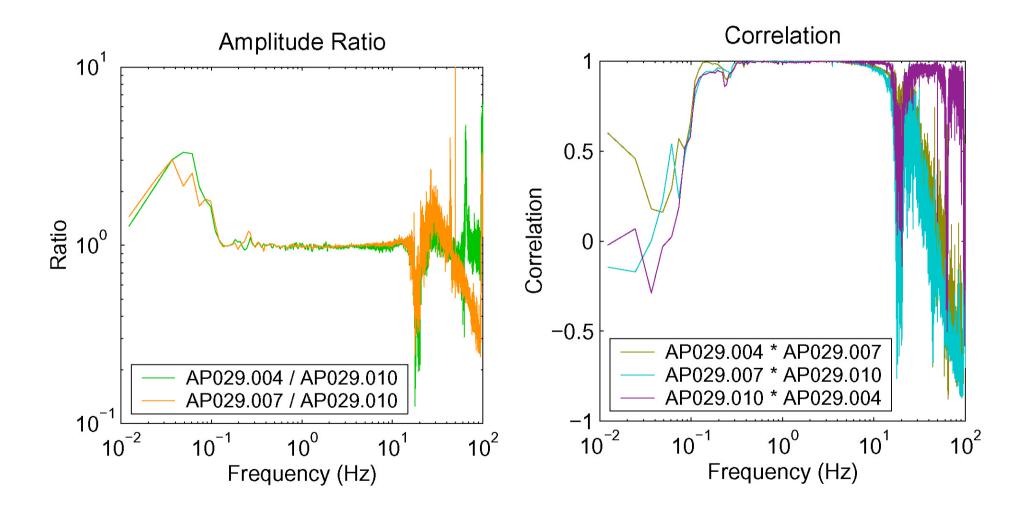


### Results (1)

#### Gain constants are provided by GURALP.



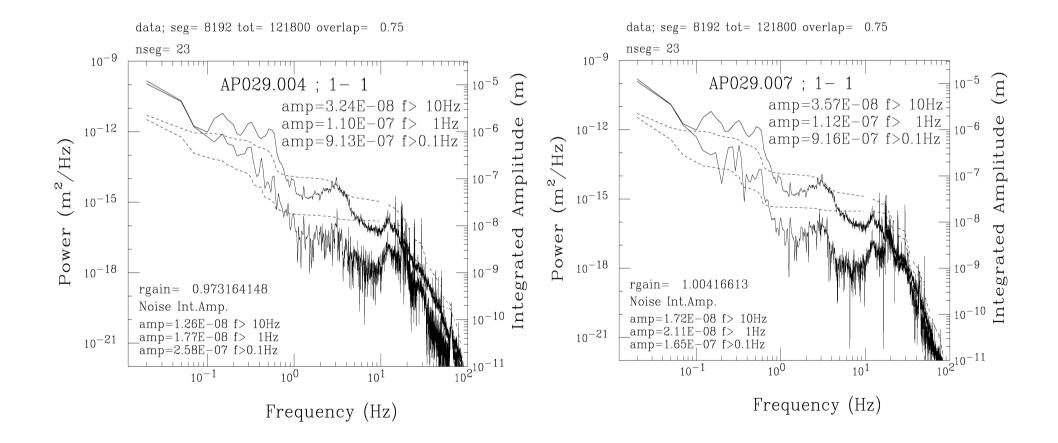
#### Results (2)



#### Results (3)

## "noise" estimation by PSD(1-C(PSDxPSD')<sup>1/2</sup>), PSD'=ch10

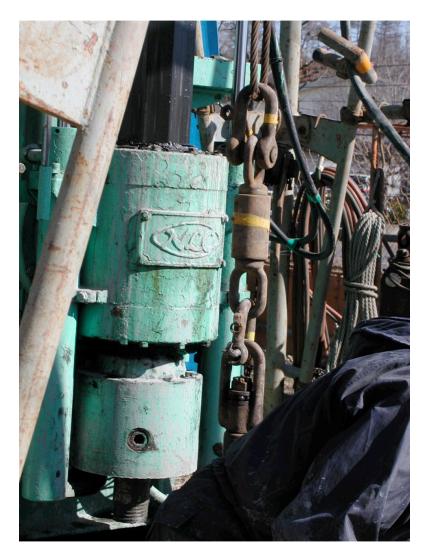
, which is true for perfect gain constants, PSD=signal +noise.



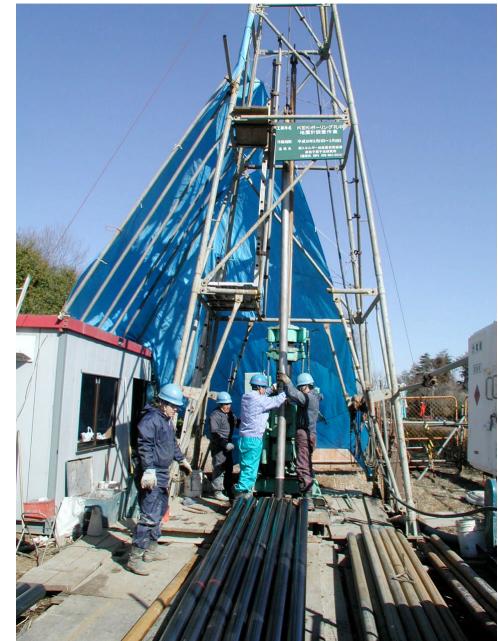




## Boring Process(2)



#### Boring machine NLC



## Boring Process(3)





Installing glass beads to anchore the sensor.

### Setting CMG40T at GL



The sensor is surrounded by sand, and thermal insulators fill the manhole ( about 1m deep).

### GM Measurement

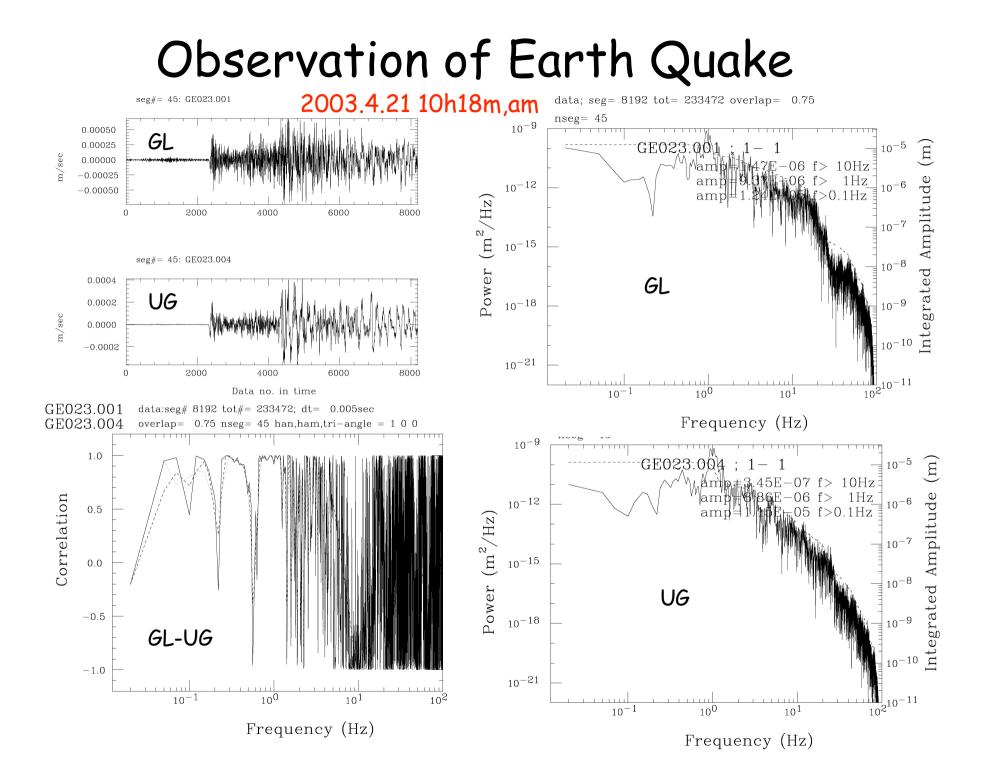
Measurement began at 10pm on 17th April, 2003.

For the moment, 4 times per day at 4am, 10am, 4pm, 10pm.

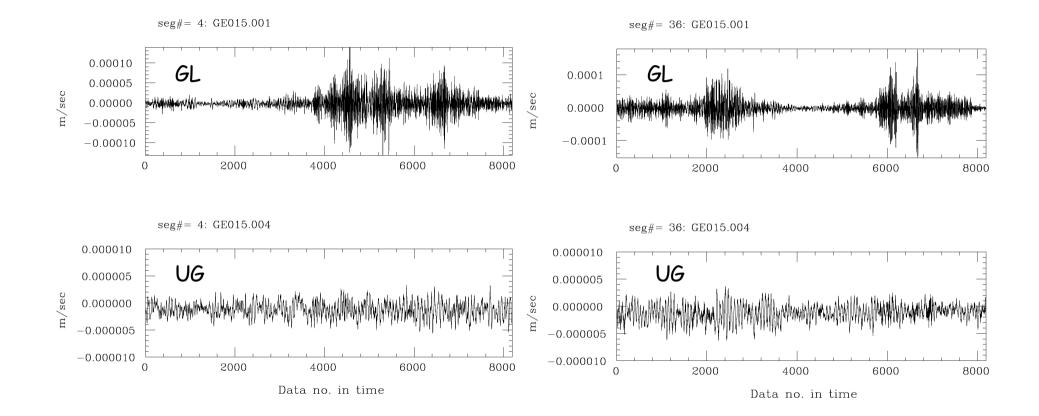
Data are taken for 30 minutes each at 200 Hz.

The data are segmented into 40.96 sec (8192 data points) for FFT analysis with 75% overlap and Hanning window function. So, there are 69 segments for 30 minutes.

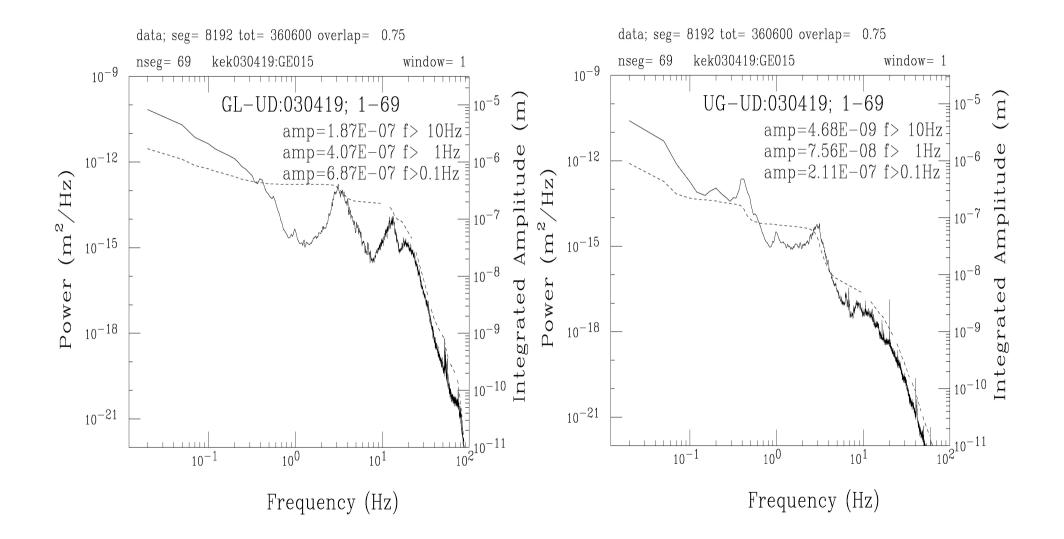
Power spectra, coherences and correlations are averages of the segments.



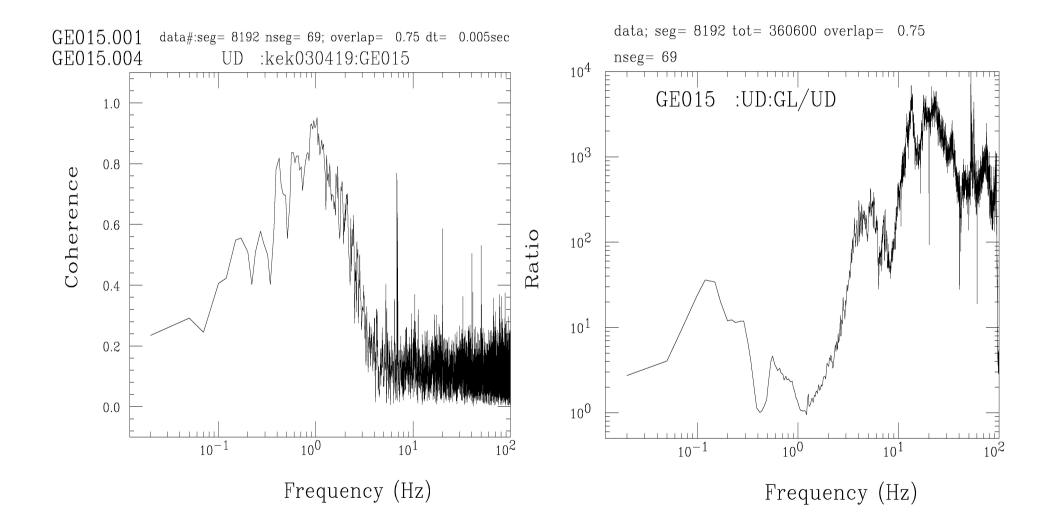
#### 2003.4.19, 10am (1)



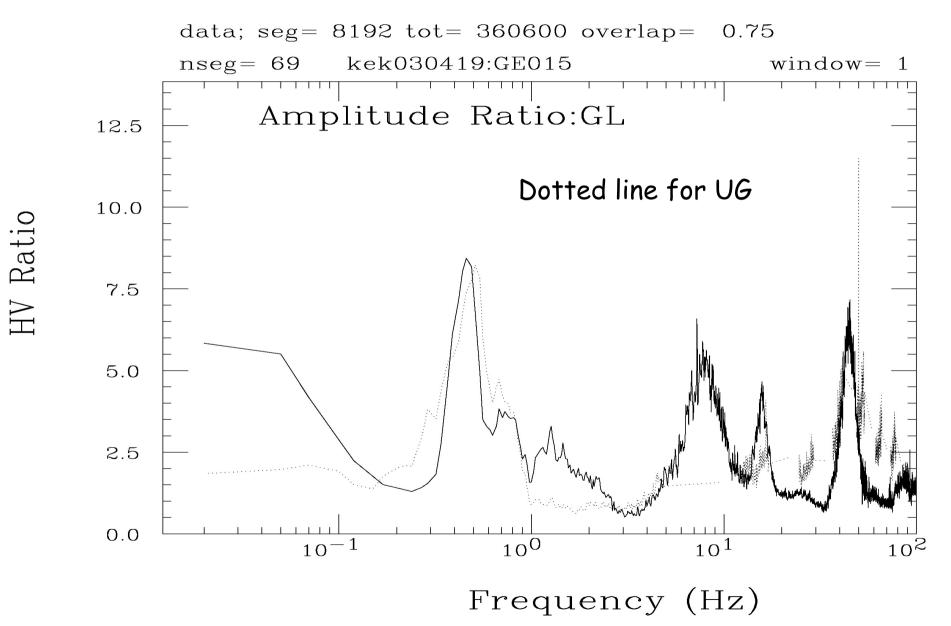
#### 2003.4.19, 10am (2)



#### 2003.4.19, 10am (3)

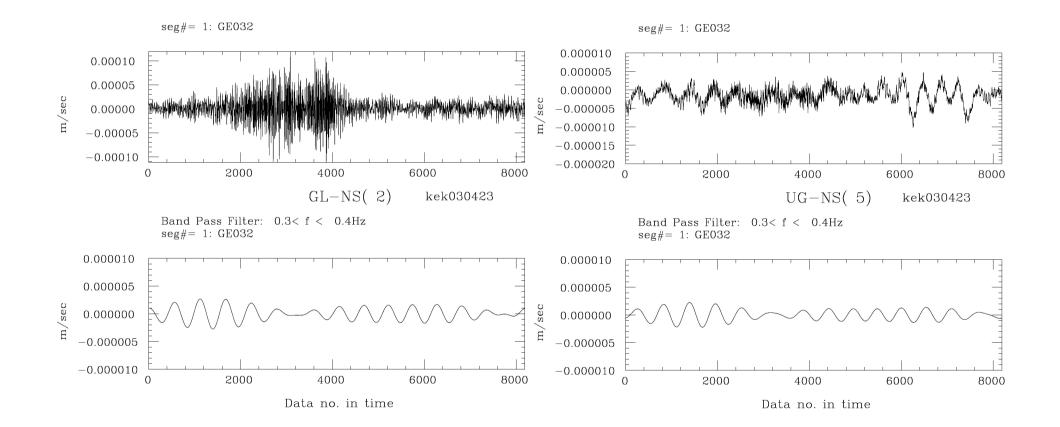


#### 2003.4.19, 10am (4)

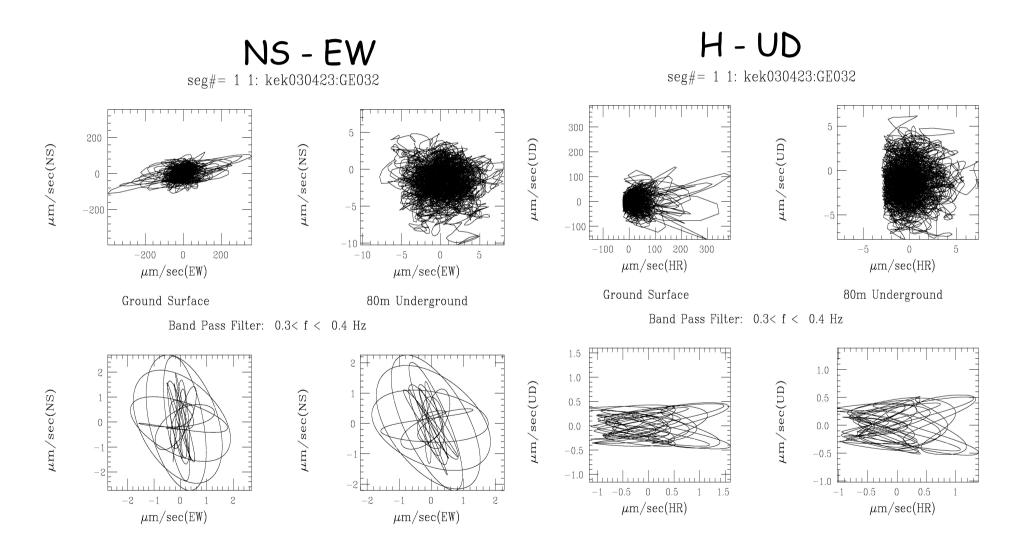


### Peak at 0.3~0.4 Hz (1)

2003.4.23, 4pm



### Peak at 0.3~0.4 Hz (1)

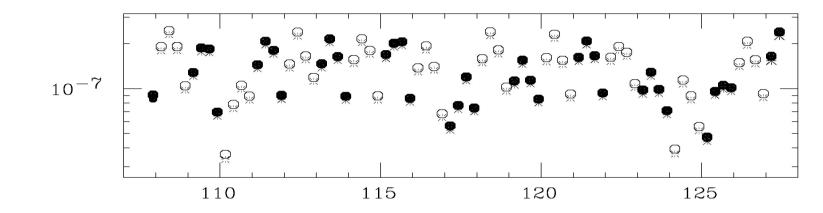


#### UD:Integrated Amplitude at f>10Hz for 2003.4.17,10pm ~ 2003.5.7,10am

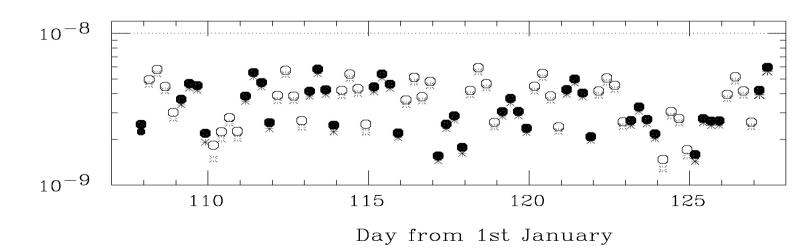
GL-UD : 10.0Hz

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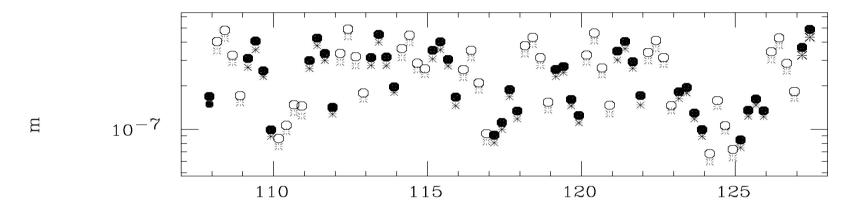


UG-UD : 10.0Hz



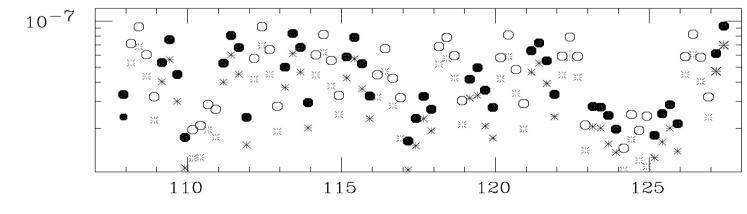
#### UD:Integrated Amplitude at f>1Hz for 2003.4.17,10pm ~ 2003.5.7,10am

GL-UD : 1.0Hz



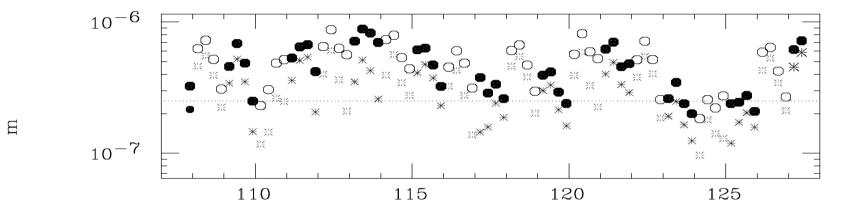
UG-UD : 1.0Hz

E

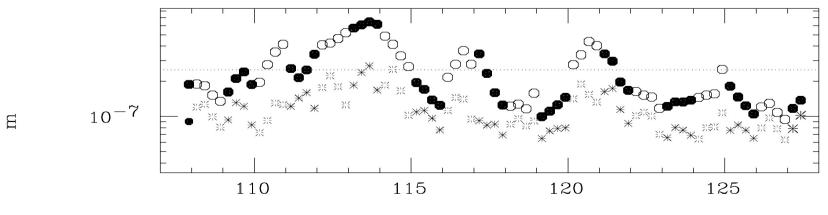


#### UD:Integrated Amplitude at f>0.1Hz for 2003.4.17,10pm ~ 2003.5.7,10am

 $\text{GL-UD}: \quad 0.1\text{Hz}$ 

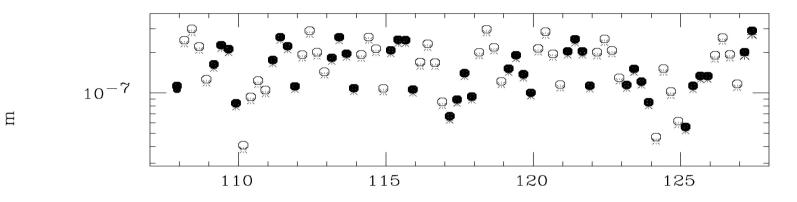


UG-UD : 0.1Hz



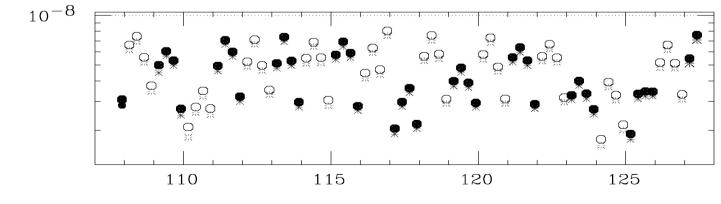
#### NS:Integrated Amplitude at f>10Hz for 2003.4.17,10pm ~ 2003.5.7,10am

 $\mathrm{GL-NS}$  : 10.0Hz



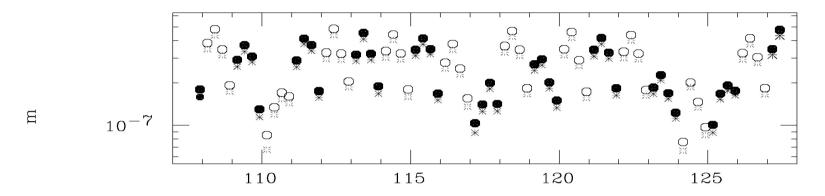
UG-NS : 10.0Hz

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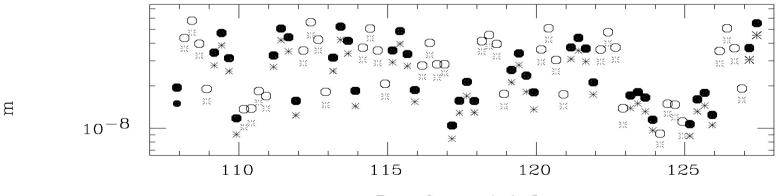


#### NS:Integrated Amplitude at f>1Hz for 2003.4.17,10pm ~ 2003.5.7,10am

 $\rm GL{-}NS$  : 1.0Hz

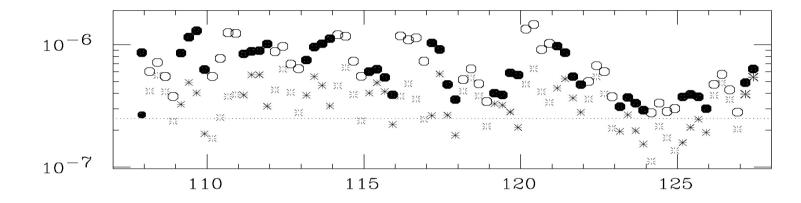


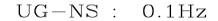
UG-NS : 1.0Hz

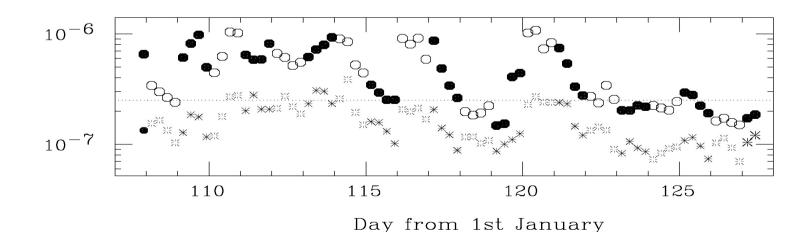


#### NS:Integrated Amplitude at f>0.1Hz for 2003.4.17,10pm ~ 2003.5.7,10am

GL-NS : 0.1Hz





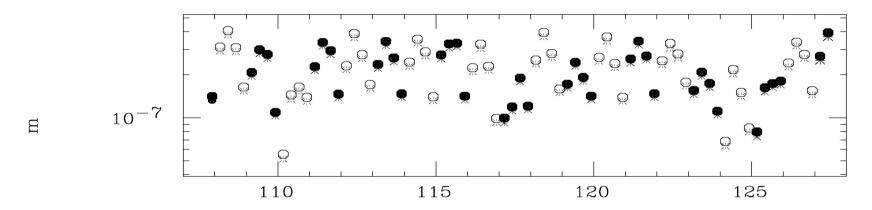


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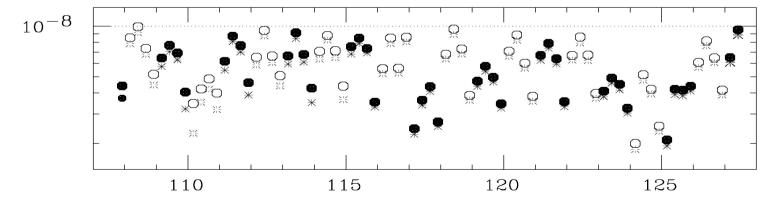
#### EW:Integrated Amplitude at f>10Hz for 2003.4.17,10pm ~ 2003.5.7,10am

GL-EW : 10.0Hz



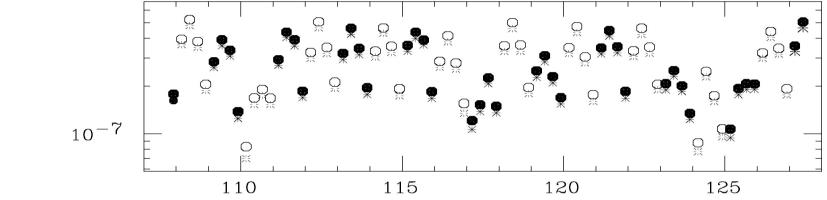
UG-EW : 10.0Hz

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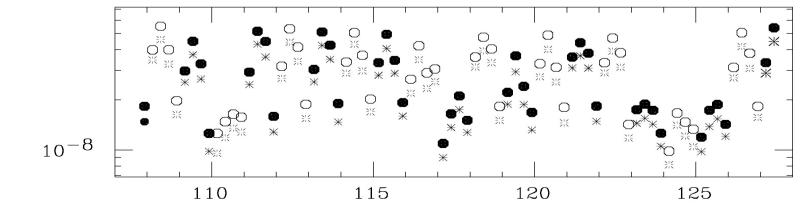


#### EW:Integrated Amplitude at f>1Hz for 2003.4.17,10pm ~ 2003.5.7,10am

GL-EW : 1.0Hz



UG-EW : 1.0Hz



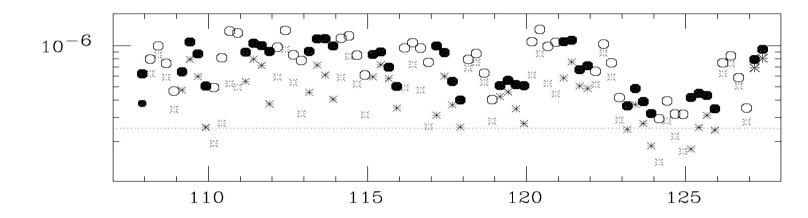
Day from 1st January

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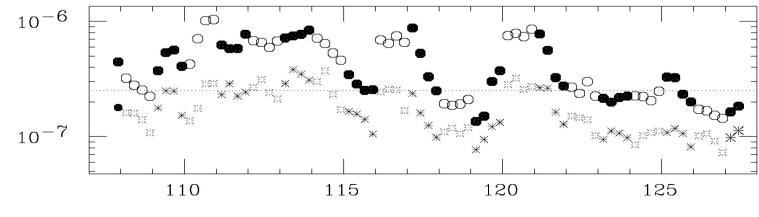
Ξ

#### EW:Integrated Amplitude at f>0.1Hz for 2003.4.17,10pm ~ 2003.5.7,10am

GL-EW : 0.1Hz



UG-EW : 0.1Hz

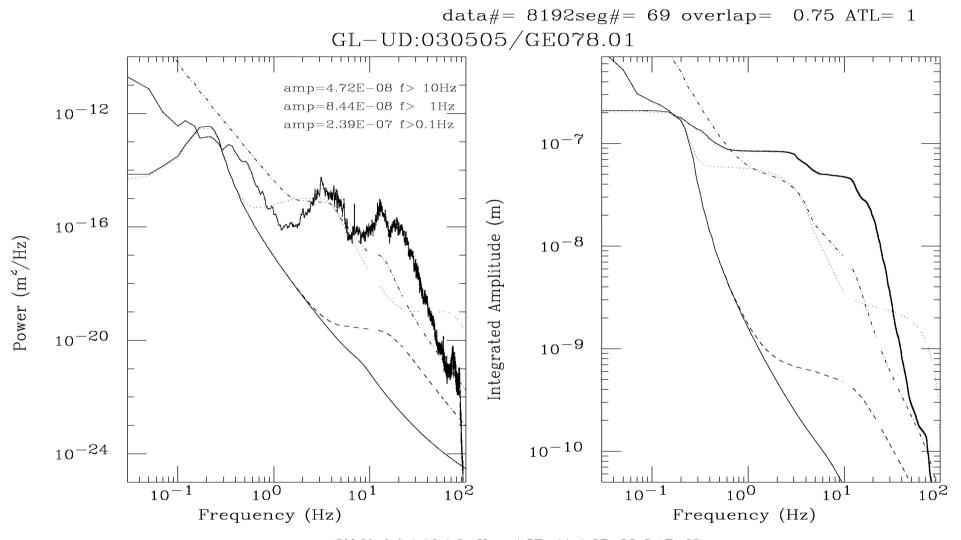


Day from 1st January

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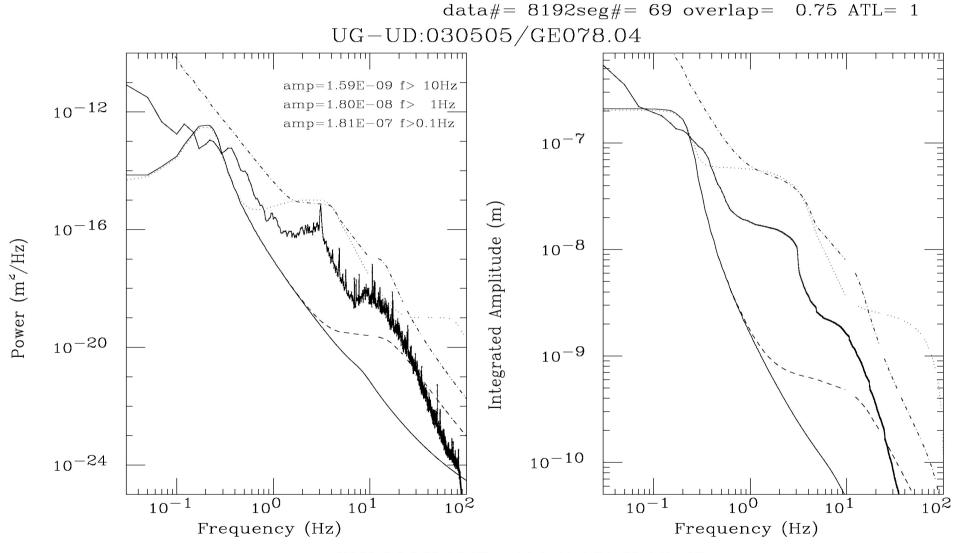
#### GM Models of A,B,C and -36m 2003.5.5, 4am



GM Model A:10,1,0.1Hz= 4.5E-11 1.6E-09 2.1E-07 GM Model B:10,1,0.1Hz= 4.7E-10 1.7E-09 2.1E-07 GM Model C:10,1,0.1Hz= 3.6E-09 5.7E-08 2.0E-07 Konoike36m:10,1,0.1Hz= 7.8E-09 6.1E-08 1.1E-06

## GM Models of A,B,C and -36m

#### 2003.5.5, 4am



GM Model A:10,1,0.1Hz= 4.5E-11 1.6E-09 2.1E-07 GM Model B:10,1,0.1Hz= 4.7E-10 1.7E-09 2.1E-07 GM Model C:10,1,0.1Hz= 3.6E-09 5.7E-08 2.0E-07 Konoike36m:10,1,0.1Hz= 7.8E-09 6.1E-08 1.1E-06