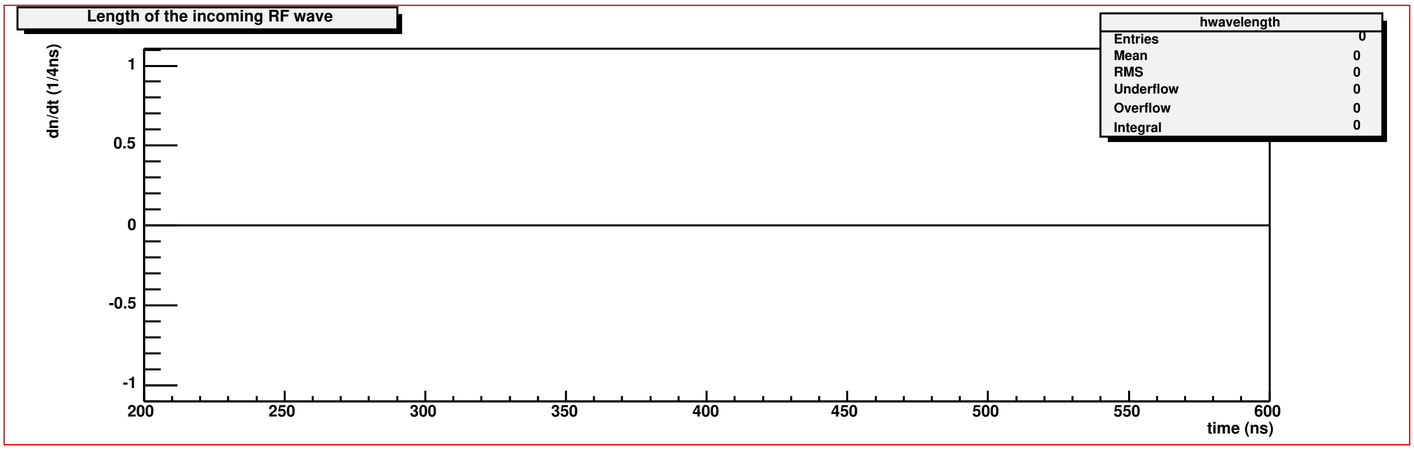

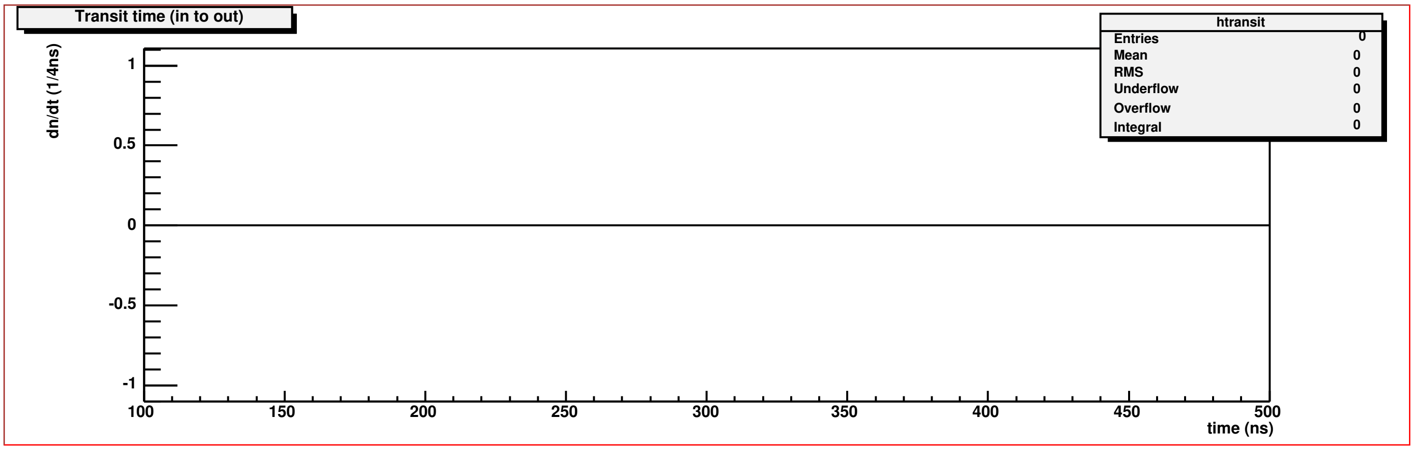

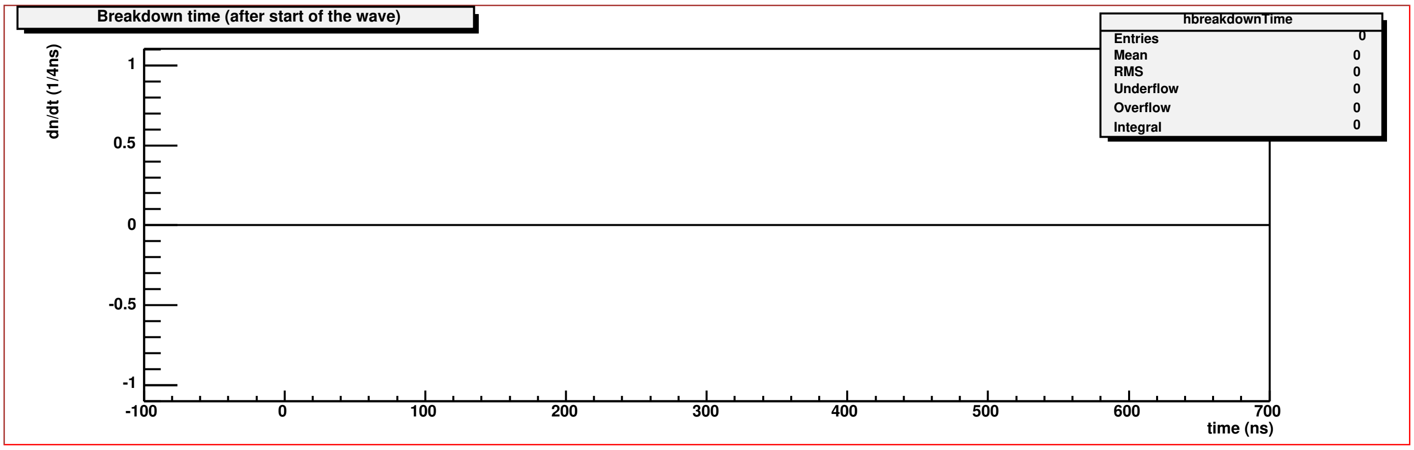

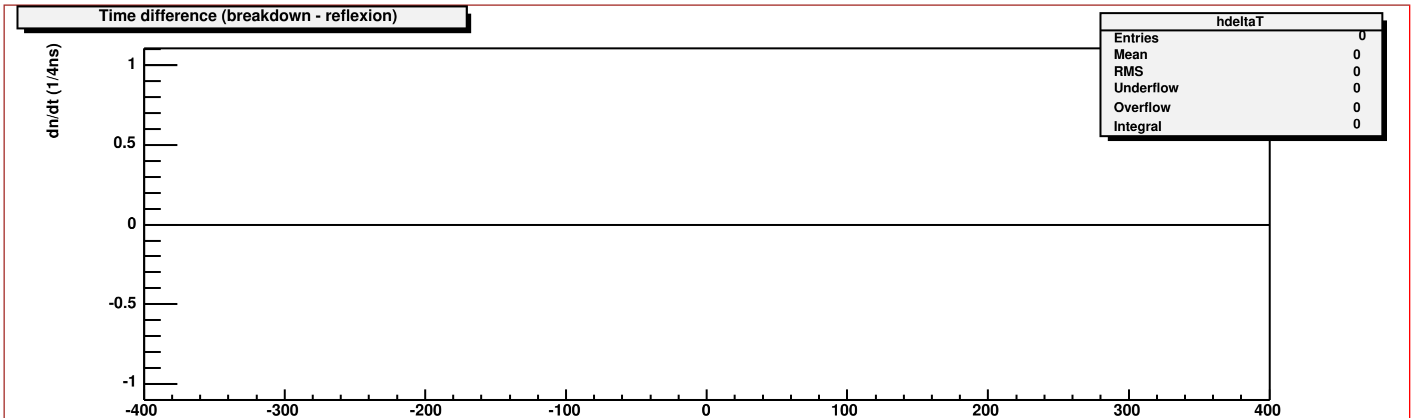

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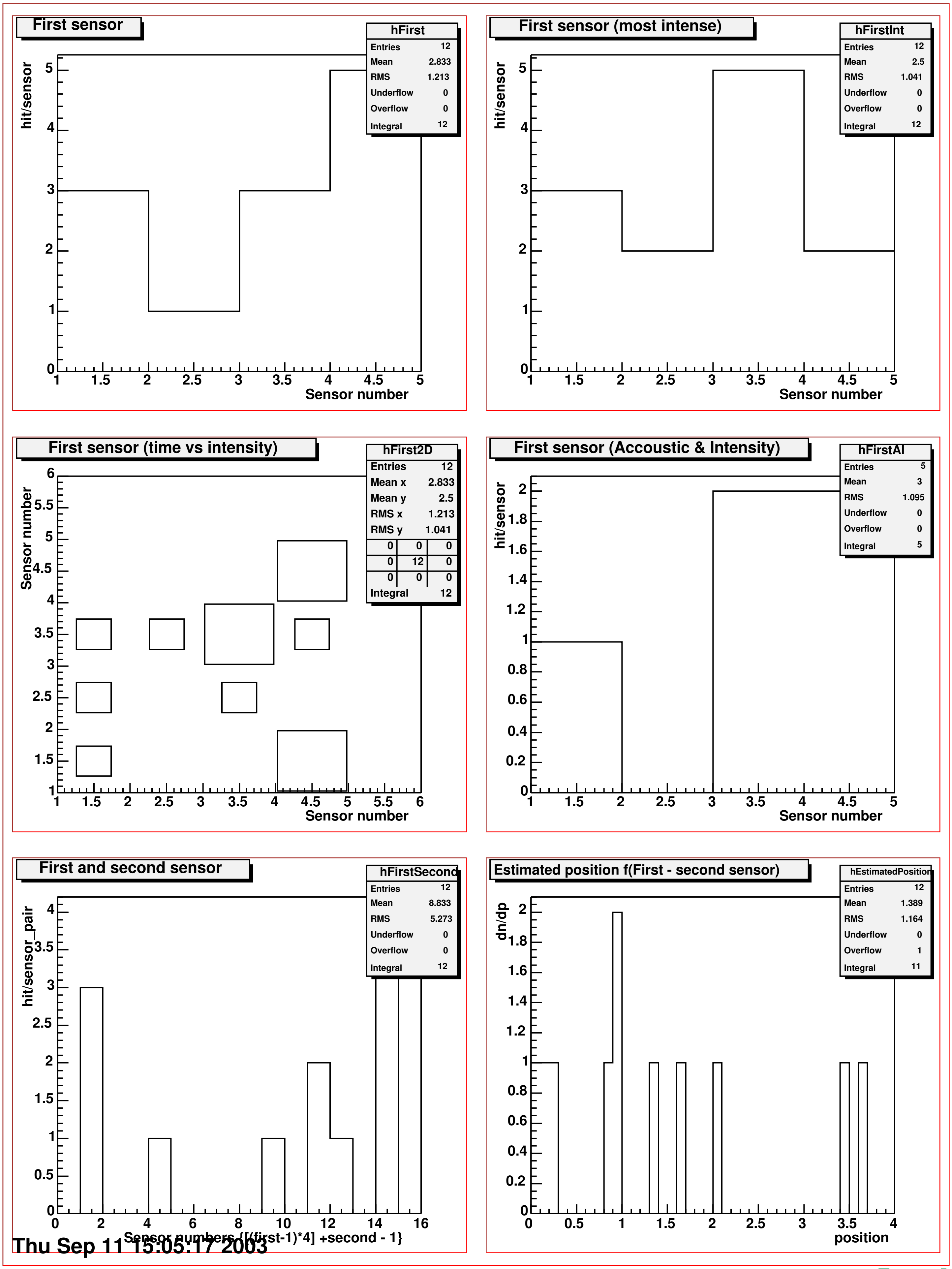
First sensor
hFirst
Entries 12
Mean 2.833
RMS 1.213
Underflow 0
Overflow 0
Integral 12
hit/sensor
Sensor number
First sensor (most intense)
hFirstInt
Entries 12
Mean 2.5
RMS 1.041
Underflow 0
Overflow 0
Integral 12
hit/sensor
Sensor number
First sensor (time vs intensity)
hFirst2D
Entries 12
Mean x 2.833
Mean y 2.5
RMS x 1.213
RMS y 1.041
0 0 0
0 12 0
0 0 0
Integral 12
Sensor number
Sensor number
First sensor (Accoustic & Intensity)
hFirstAI
Entries 5
Mean 3
RMS 1.095
Underflow 0
Overflow 0
Integral 5
hit/sensor
Sensor number
First and second sensor
hFirstSecond
Entries 12
Mean 8.833
RMS 5.273
Underflow 0
Overflow 0
Integral 12
hit/sensor_pair
Sensor numbers {[(first-1)*4] +second - 1}
Estimated position f(First - second sensor)
hEstimatedPosition
Entries 12
Mean 1.389
RMS 1.164
Underflow 0
Overflow 1
Integral 11
dn/dp
position
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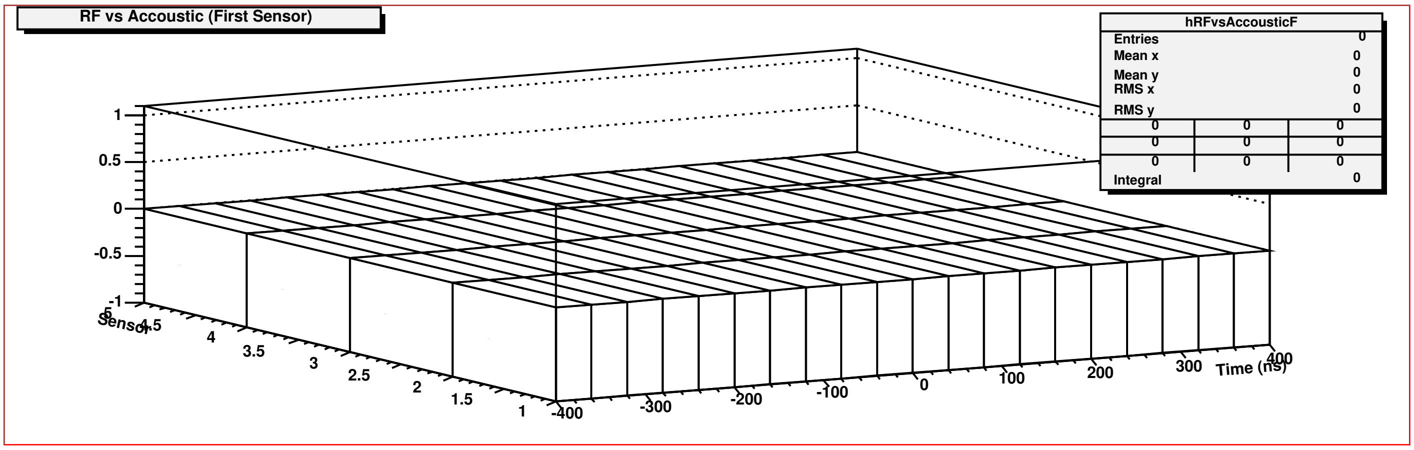

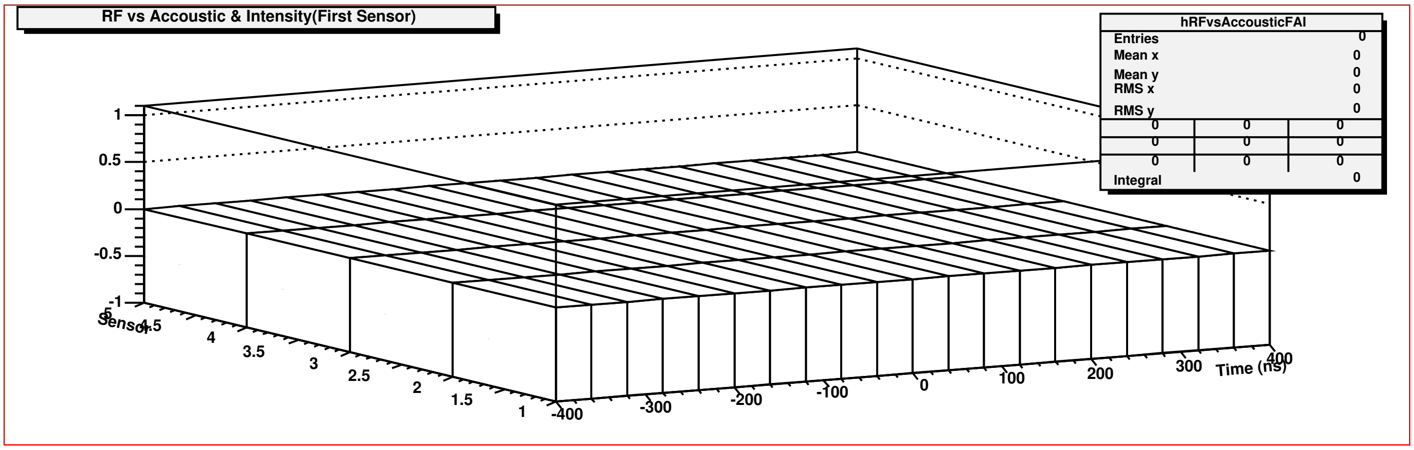

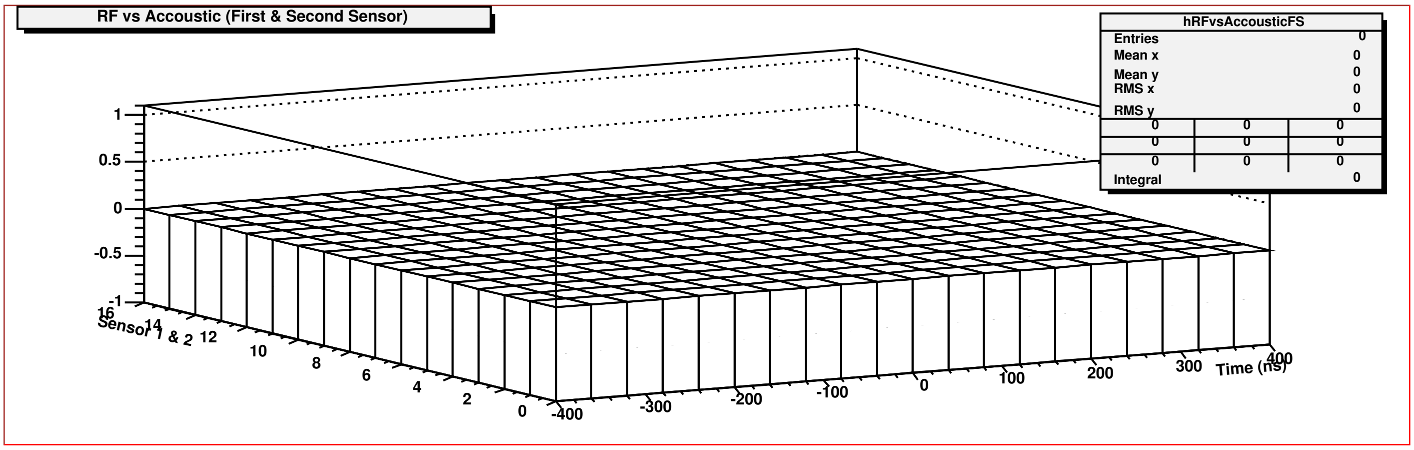

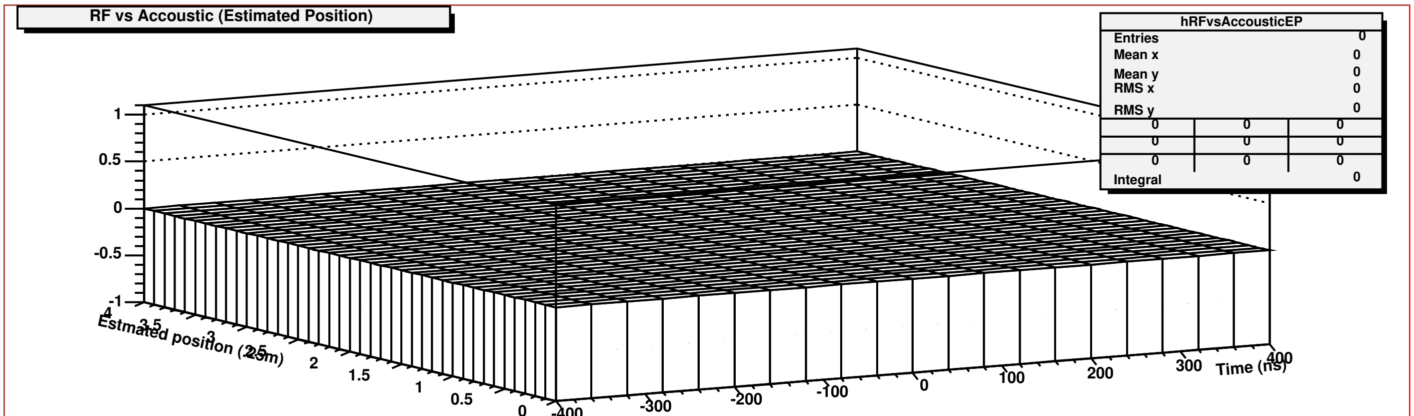

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