

# Kalman Filter Library



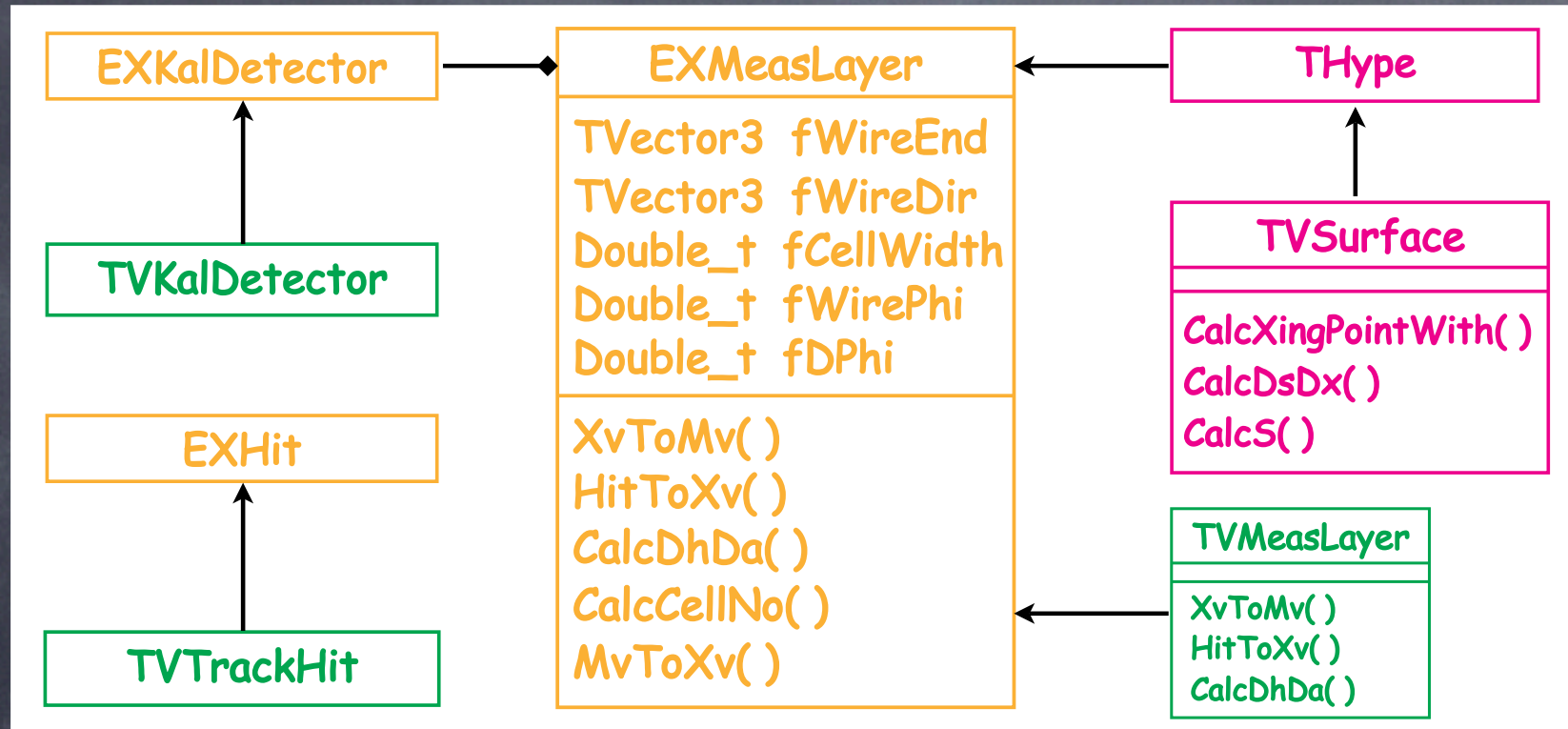
# Kalman Filter Library Features

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- KalLib: general base classes that implement algorithm
  - TVKalSystem, TVKalSite, TVKalState
- KalTrackLib: that implements pure virtuals of KalLib for track fitting purpose
- GeomLib: geometry classes that provide
  - track models (helix, straight line, ...)
  - surfaces (cylinder, hyperboloid, flat plane, ...)
  -
- Minimum number of user-implemented classes
  - **MeasLayer** : measurement layer
  - **KalDetector** : an array containing MeasLayers
    - You can put different kinds of MeasLayers
  - **Hit** : coordinate vector as defined by the MeasLayer
- Track model can change site to site which allows B-field variation along a particle trajectory

# Kalman Filter Class Organization

## CDC Example

K.Fujii @ ACFA LCWS2003

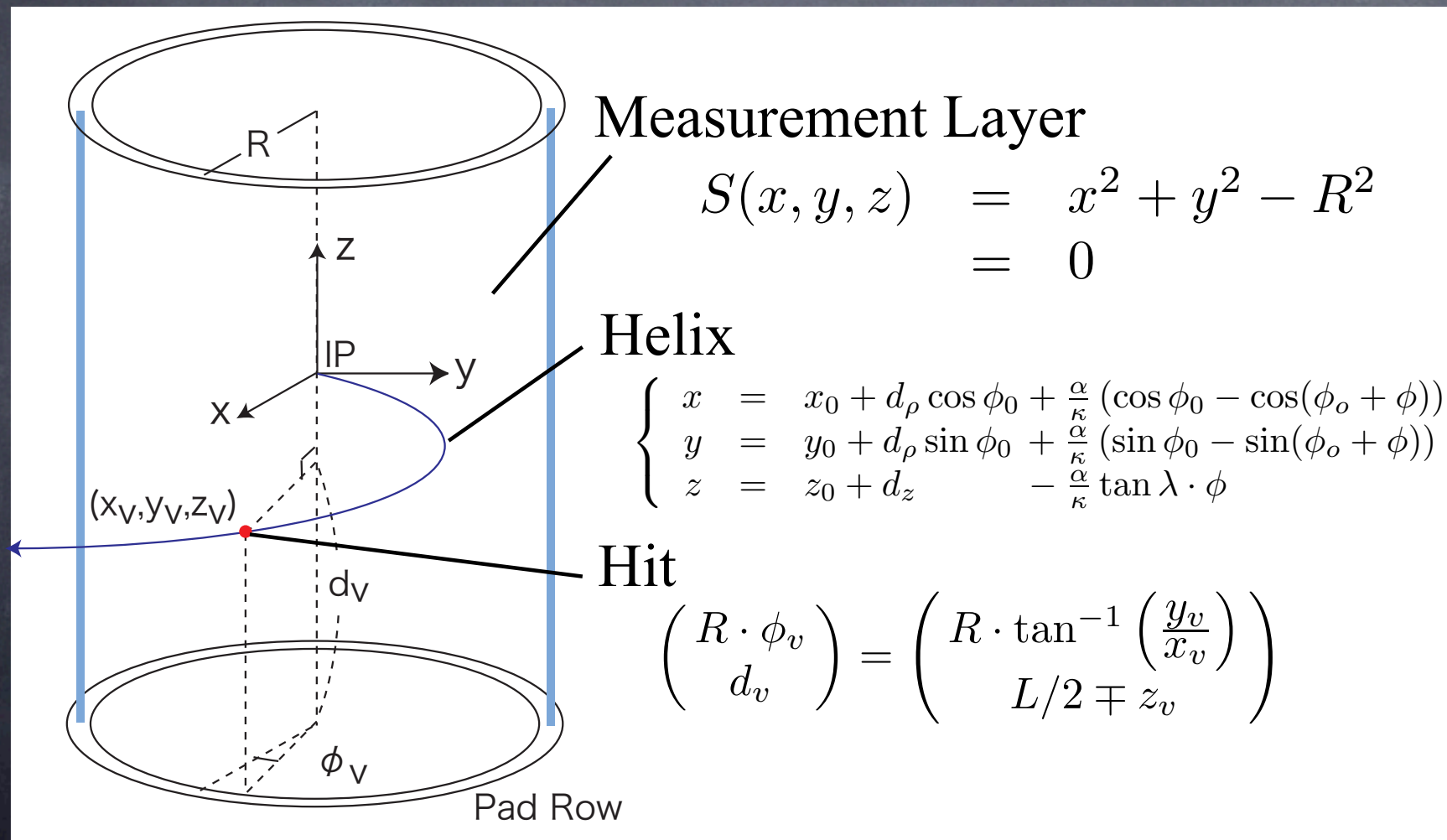


## Rest of KalTrackLib Classes



# Example of Detector Implementation

## How to define TPC





## EXMeasLayer for TPC

HitToXv

$$\begin{pmatrix} x_v \\ y_v \\ z_v \end{pmatrix} = \begin{pmatrix} R \cdot \cos \phi_v \\ R \cdot \sin \phi_v \\ \pm(L/2 - d_v) \end{pmatrix}$$

XvToMv

$$\begin{pmatrix} R \cdot \phi_v \\ d_v \end{pmatrix} = \begin{pmatrix} R \cdot \tan^{-1} \left( \frac{y_v}{x_v} \right) \\ L/2 \mp z_v \end{pmatrix}$$

# CalcDhDa

Meas.Vector Derivative w.r.t. Track Parameter Vector

$$\begin{pmatrix} \frac{\partial(R \cdot \phi_v)}{\partial a} \\ \frac{\partial d_v}{\partial a} \end{pmatrix} = \begin{pmatrix} -\frac{y_v}{R} \left( \frac{\partial x_v}{\partial a} \right) + \frac{x_v}{R} \left( \frac{\partial y_v}{\partial a} \right) \\ \mp \frac{\partial z_v}{\partial a} \end{pmatrix}$$

$$\begin{aligned} \frac{\partial \mathbf{X}(\phi(a), a)}{\partial a} &= \frac{\partial \mathbf{X}}{\partial \phi} \cdot \frac{\partial \phi}{\partial a} + \frac{\partial \mathbf{X}}{\partial a} \\ \frac{\partial \phi}{\partial a} &= - \frac{1}{\left( \frac{\partial S}{\partial \mathbf{X}} \cdot \frac{\partial \mathbf{X}}{\partial \phi} \right)} \frac{\partial S}{\partial \mathbf{X}} \cdot \frac{\partial \mathbf{X}}{\partial a} \end{aligned}$$

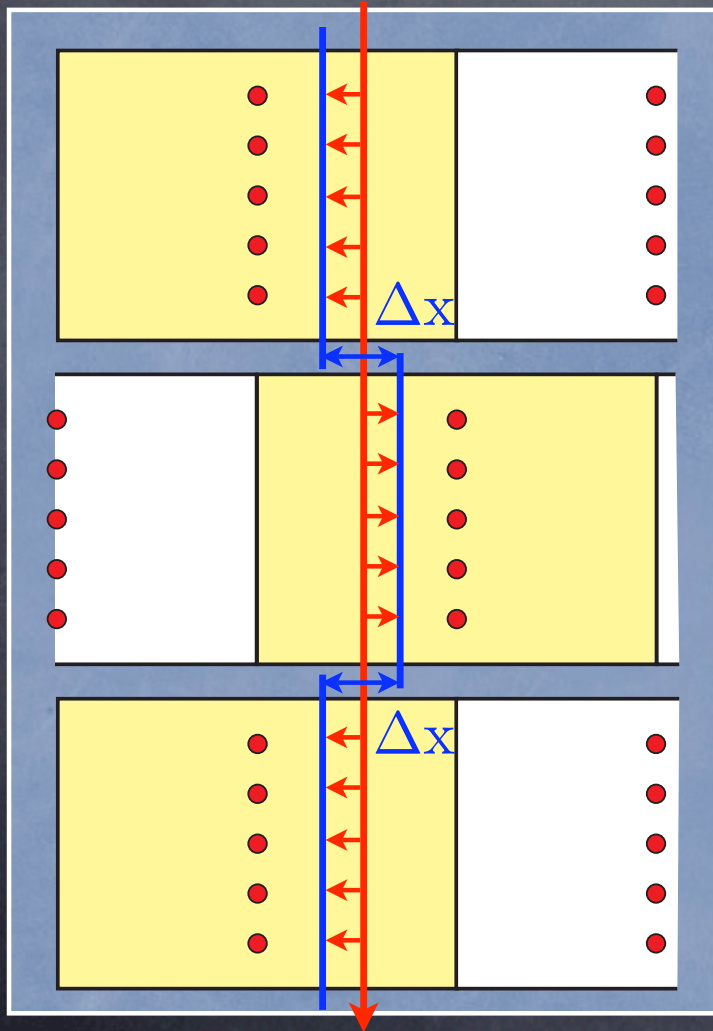
Kalman Filter Library now being imported into Satellites



# Time Stamping

## Application of Kalman Filter Library

## • In the Case of JLC-CDC



### Staggered Cells

Wrong  $T_0$  breaks a track!

$$\Delta x = 2 v_{\text{drift}} \times \Delta T_0$$

Naively we expect

$$\sigma_{\Delta T_0} \simeq \frac{\sigma_{xy}}{v_{\text{drift}} \sqrt{n}}$$

$$\sigma_{xy} = 85 \mu\text{m}$$

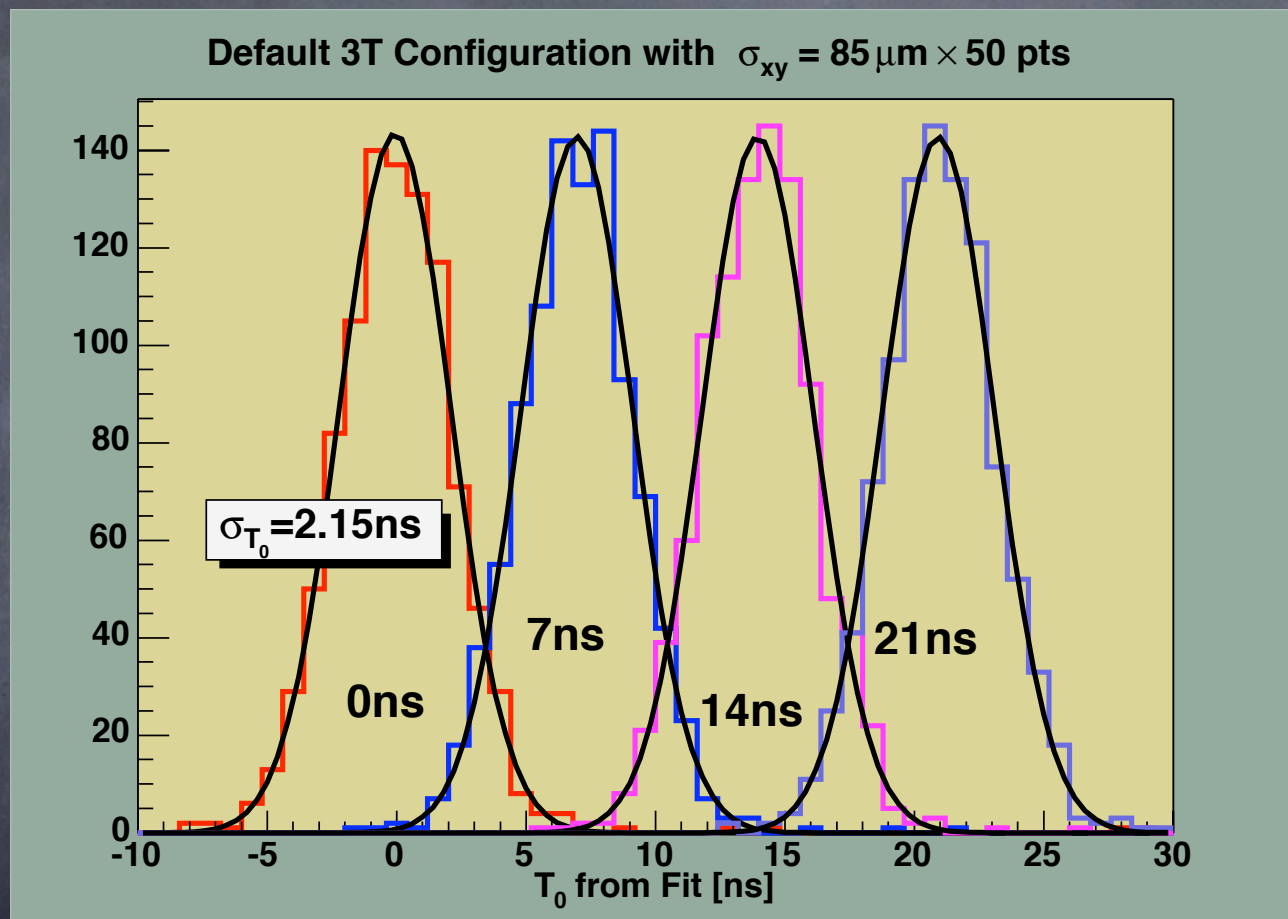
$$v_{\text{drift}} = 0.7 \text{ cm}/\mu\text{s}$$

$$n = 50$$

$$\sigma_{\Delta T_0} \simeq 1.7 \text{ ns}$$



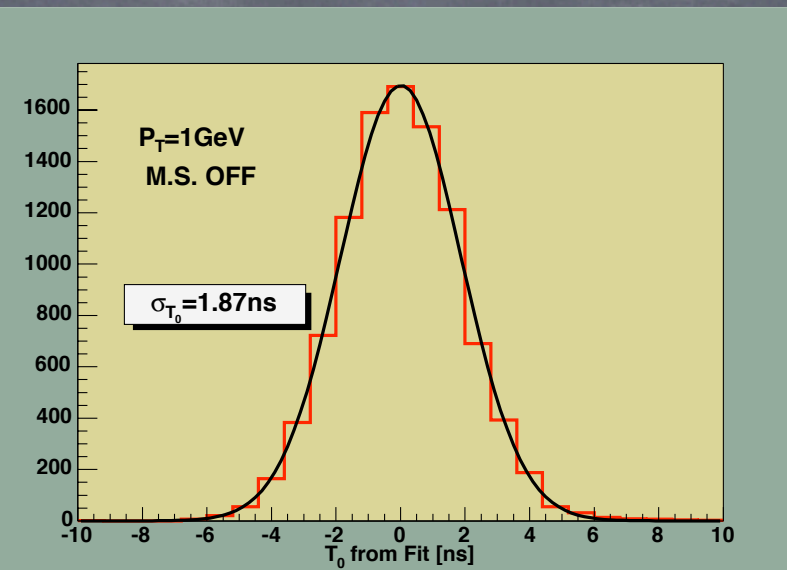
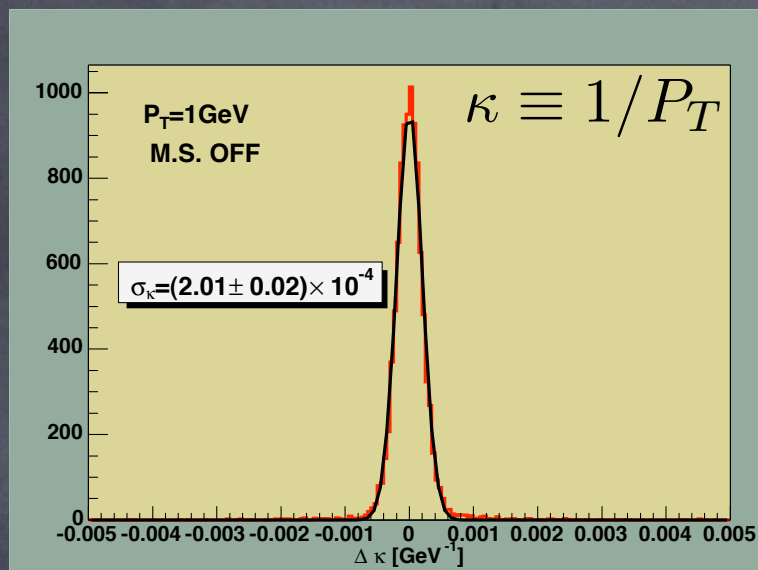
## T0 from Helix Fit (axial+stereo, 100GeV)



We can still determine  $T_0$  with  $\sim 2.2\text{ns}$  accuracy!

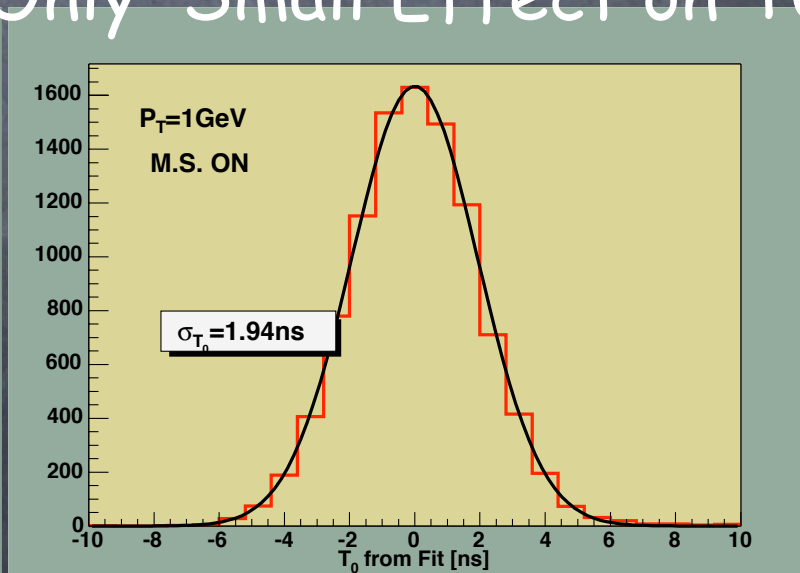
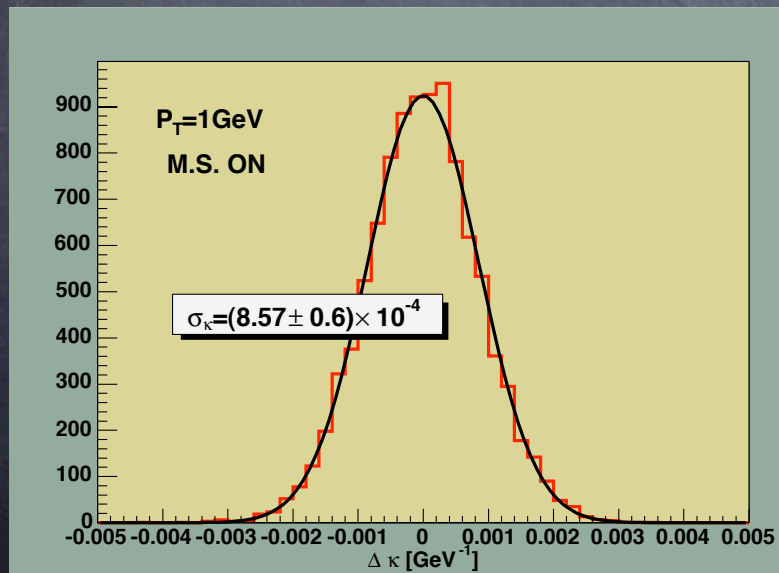
# Multiple Scattering Effects (axial+stereo, 1GeV)

MS OFF



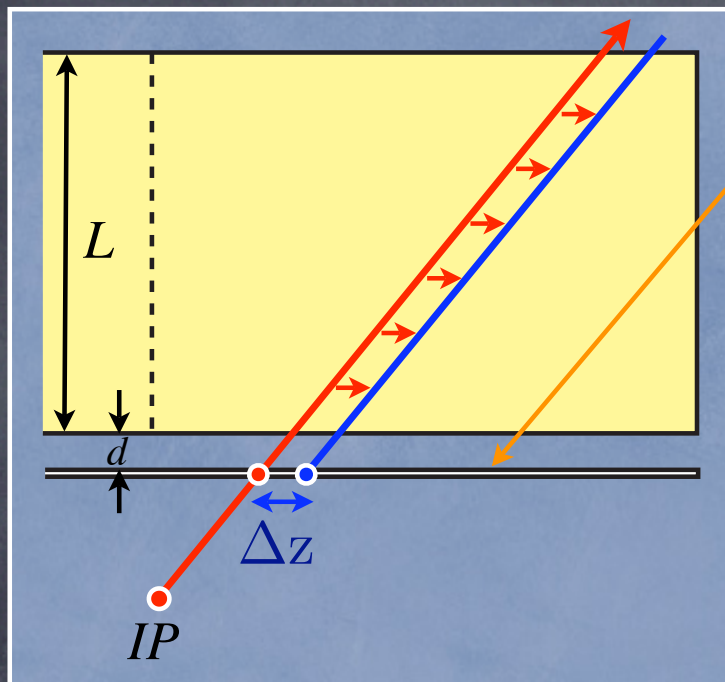
Only Small Effect on T0

MS ON





## In the Case of TPC



External Z Detector (T0 Device)

Wrong T0 makes a Z-shift!

$$\Delta z = v_{\text{drift}} \times \Delta T_0$$

Naively we expect

$$\sigma_{\Delta T_0} \simeq \frac{2\sigma_z}{v_{\text{drift}} \sqrt{n}} \left[ 1 + 3 \left( \frac{d}{L} \right) + 3 \left( \frac{d}{L} \right)^2 \right]^{-\frac{1}{2}}$$

$$\simeq \frac{2\sigma_z}{v_{\text{drift}} \sqrt{n}} \quad \text{if} \quad \left( \frac{d}{L} \right) \ll 1$$

Assuming that Z resolution of the external detector is negligible

$$\sigma_z = 500 \mu\text{m}$$

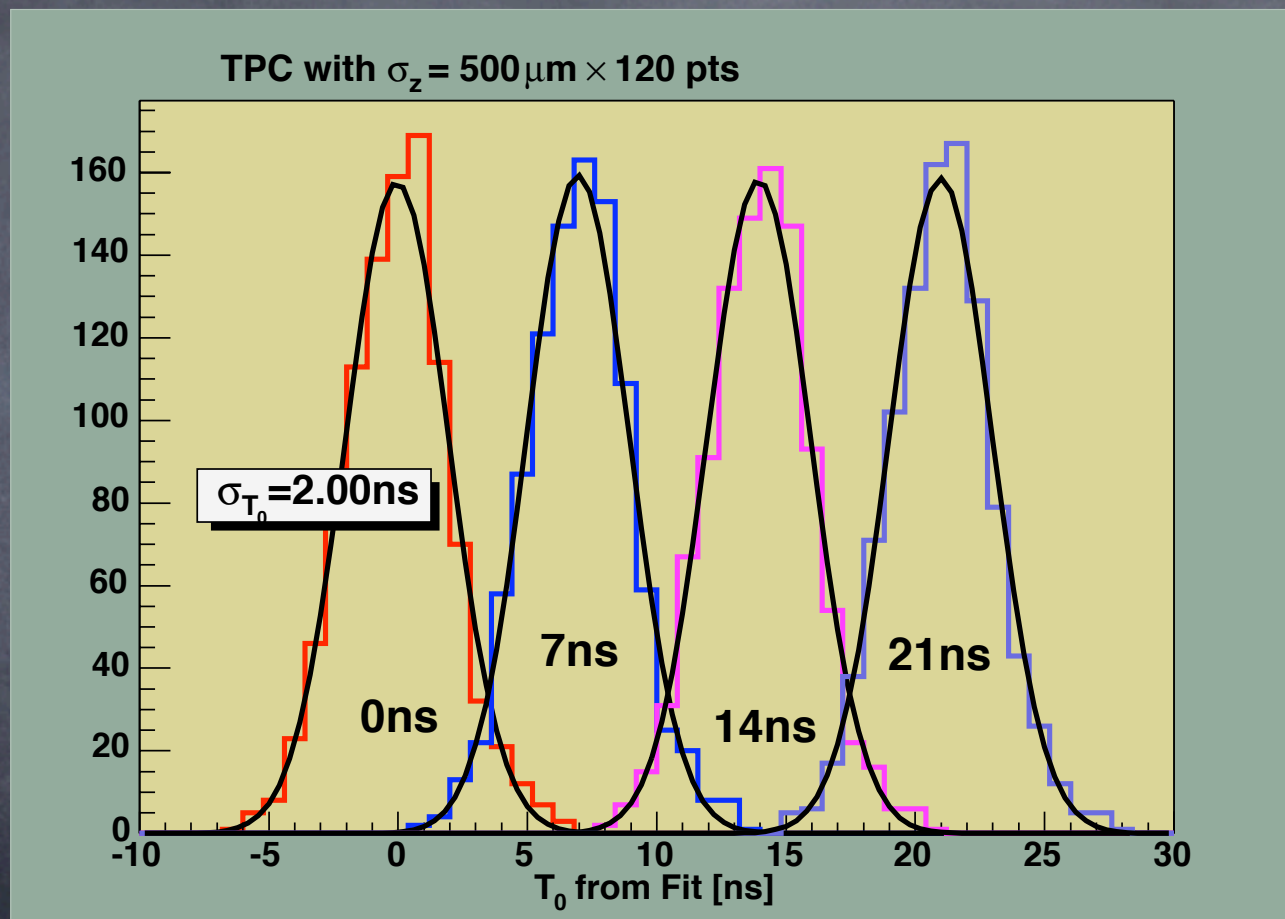
$$v_{\text{drift}} = 5 \text{ cm}/\mu\text{s}$$

$$n = 120$$



$$\sigma_{\Delta T_0} \simeq 2.0 \text{ ns}$$

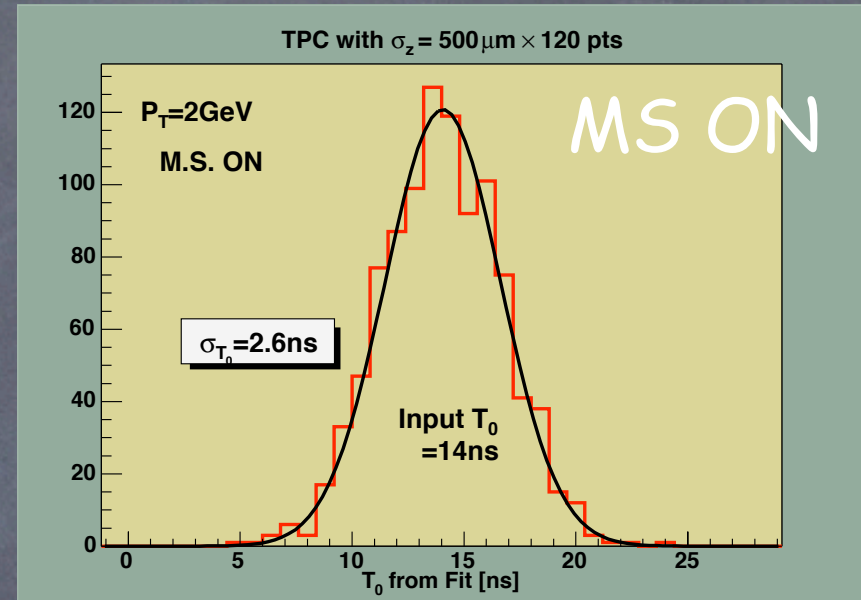
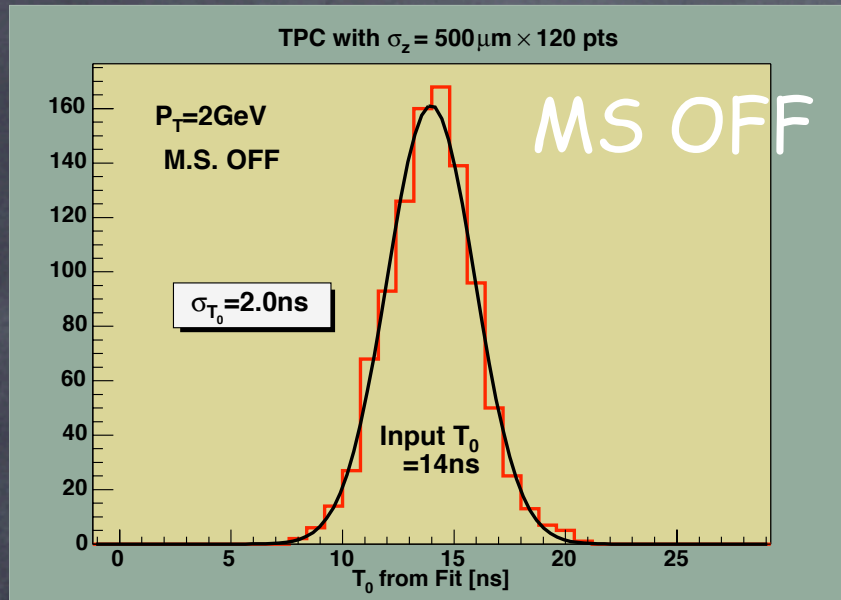
## T0 from Helix Fit (d=5cm, 100GeV)



We can determine  $T_0$  with  $\sim 2.0\text{ns}$  accuracy as expected!



## Multiple Scattering Effects ( $d=5\text{cm}, 0.6\%X_0, 2\text{GeV}$ )



MS Effect more significant than for CDC

This is probably due to the fact that there is only a single break point to decide  $T_0$ .

The material thickness between TPC and  $T_0$  detector does not matter as long as it stays just in front of the  $T_0$  detector.

$0.6\%X_0$  to  $3.0\%X_0 \rightarrow 2\%$  shift in  $T_0$  resolution