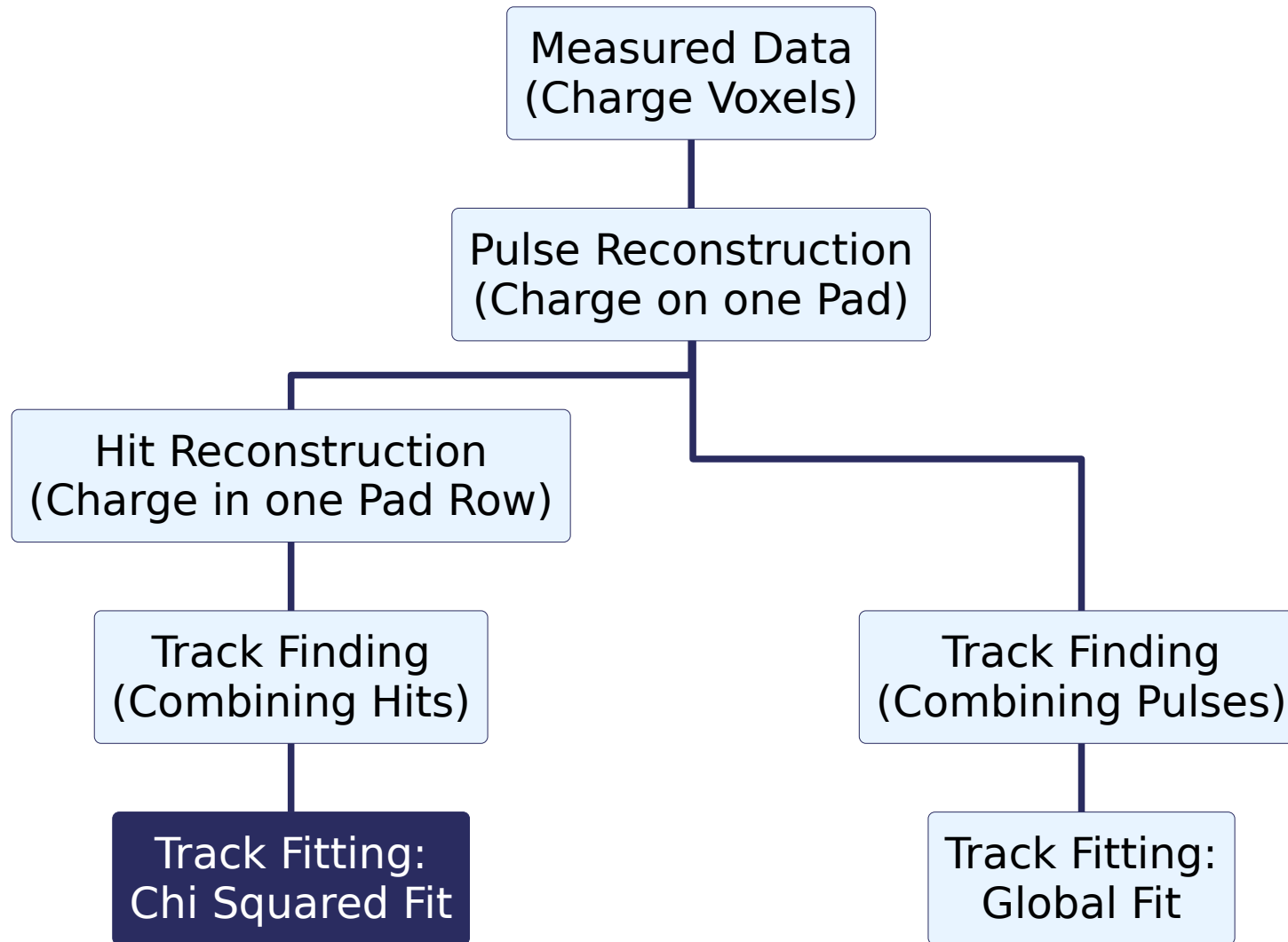


Chi Squared Fit



Least Squares Method

- **N measurements at points y_i** (the measurement points are given by the pad rows)
- **Variables x_i with error σ_i** (the x coordinate of the hit is the measurement)
- **Fit function: $f(y; a_1, a_2, \dots, a_M)$, a_j : parameters to be determined**
- **$N > M$!** (more measurement points than parameters needed!)
- **For the best values a_j , sum S is a minimum :**

$$S = \sum_{i=1}^N \left[\frac{x_{(i)} - f(y_i, a_j)}{\sigma_i} \right]^2 \rightarrow \frac{\partial S}{\partial a_j} = 0, j = 1 \dots M$$

- **for S to be a real chi-square, x_i must be Gaussian distributed with mean $f(y_i; a_j)$ and variance σ_i^2**

Chi Squared Fit

- Straight Line: $x = f(y) = ay + b$

a: SlopeX
b: InterceptX

- So, in this case: $S = \sum_i \frac{(x_i - ay_i - b)^2}{\sigma_i^2}$ and

$$\frac{\partial S}{\partial a} = -2 \sum_i \frac{(x_i - ay_i - b)y_i}{\sigma_i^2} = 0 \quad \text{and} \quad \frac{\partial S}{\partial b} = -2 \sum_i \frac{(x_i - ay_i - b)}{\sigma_i^2} = 0$$

with:

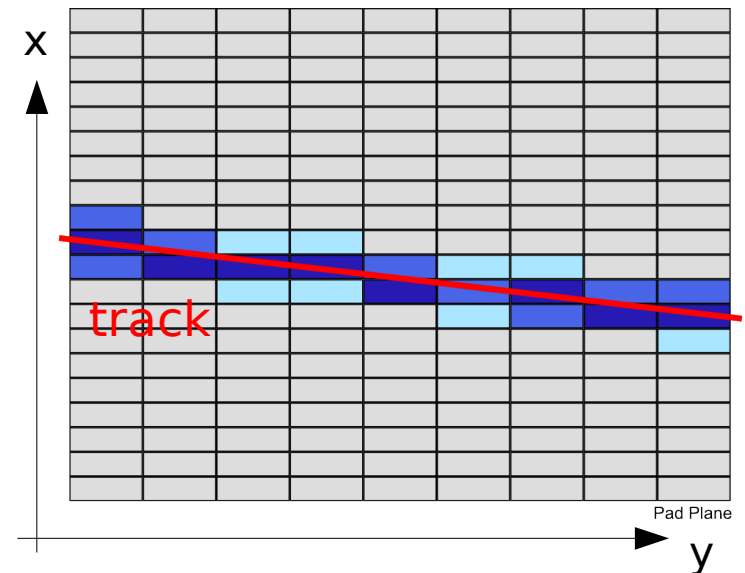
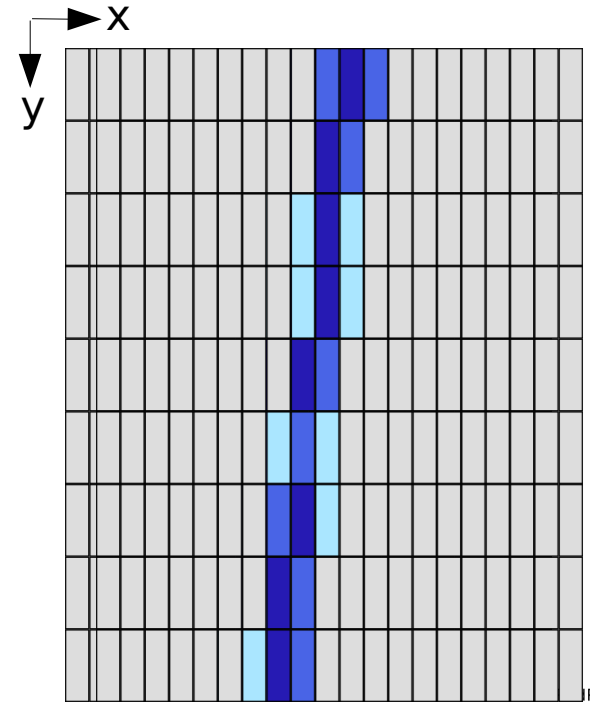
$$A = \sum_i \frac{y_i}{\sigma_i^2} \quad B = \sum_i \frac{1}{\sigma_i^2} \quad C = \sum_i \frac{x_i}{\sigma_i^2}$$

$$D = \sum_i \frac{y_i^2}{\sigma_i^2} \quad E = \sum_i \frac{x_i y_i}{\sigma_i^2} \quad F = \sum_i \frac{x_i^2}{\sigma_i^2}$$

this results in $2(-E + aD + bA) = 0,$
 $2(-C + aA + bB) = 0$

and the parameters a and b are given by:

$$a = \frac{EB - CA}{DB - A^2} \quad \text{and} \quad b = \frac{DC - EA}{DB - A^2}$$

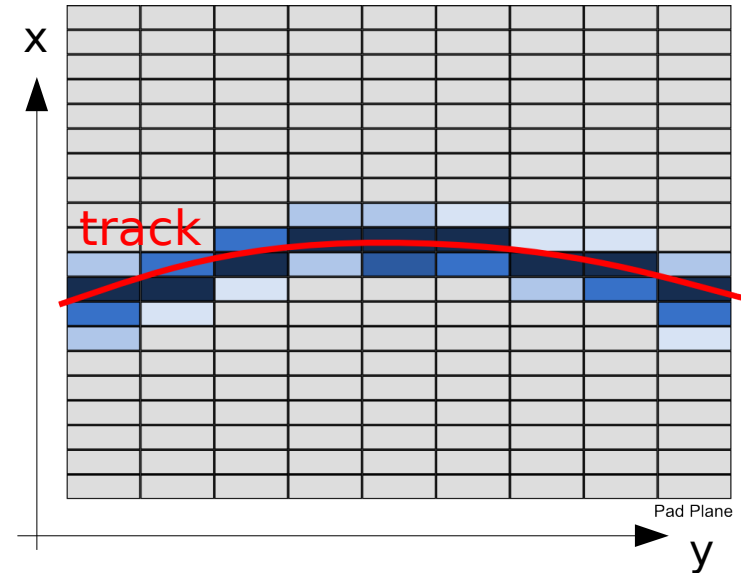


Chi Squared Fit

- 2nd degree polynomial: $x = f(y) = a y^2 + b y + c$
- also in rotated coordinate system

- This leads to
$$S = \sum_i \frac{(x_i - a y_i^2 - b y_i - c)^2}{\sigma_i^2}$$

(minimized numerically)



$$\text{Radius } R = \frac{a}{2}, \quad \text{Curvature } C = \frac{1}{R}$$

Center $(x_0, y_0) \rightarrow$ solve equation system:

$$(x - x_0)^2 + (y - y_0)^2 = R^2 \quad \text{for 2 points } (x_1, y_1), (x_2, y_2)$$

Fast fit method, results can be used for circle fit

Chi Squared Fit

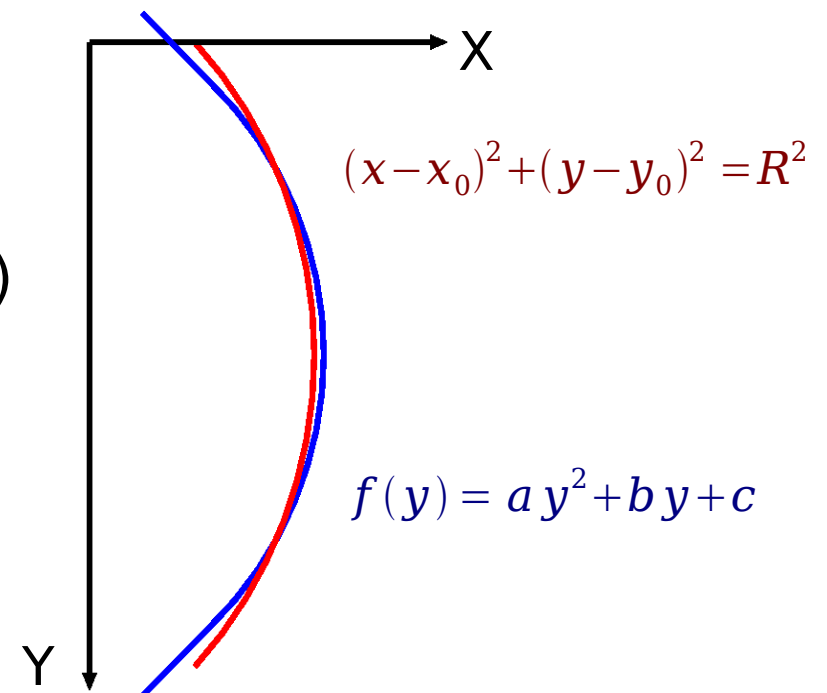
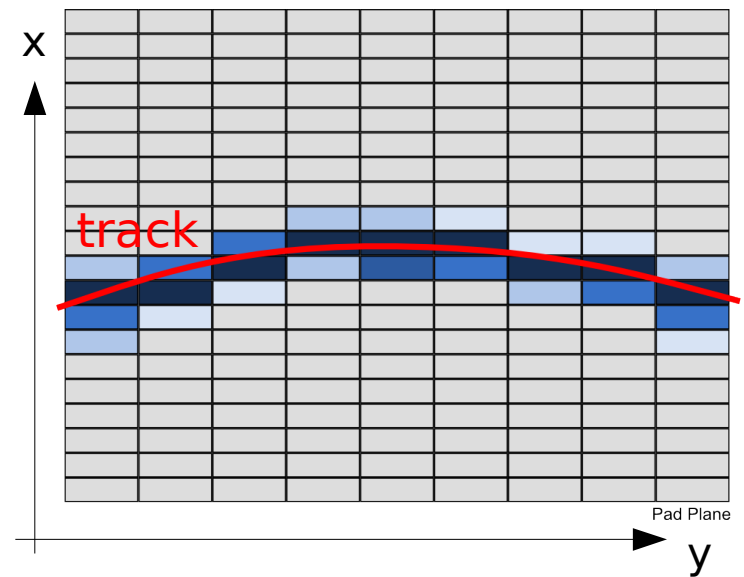
- Circle Fit: $(x-x_0)^2+(y-y_0)^2=R^2$
- also in rotated coordinate system, so the function is:

$$x = f(y) = x_0 \pm \sqrt{\frac{1}{C^2} - (y-y_0)^2}$$

- This leads to

$$S = \sum_i \frac{\left(x_i - x_0 \pm \sqrt{\frac{1}{C^2} - (y_i - y_0)^2} \right)^2}{\sigma_i^2}$$

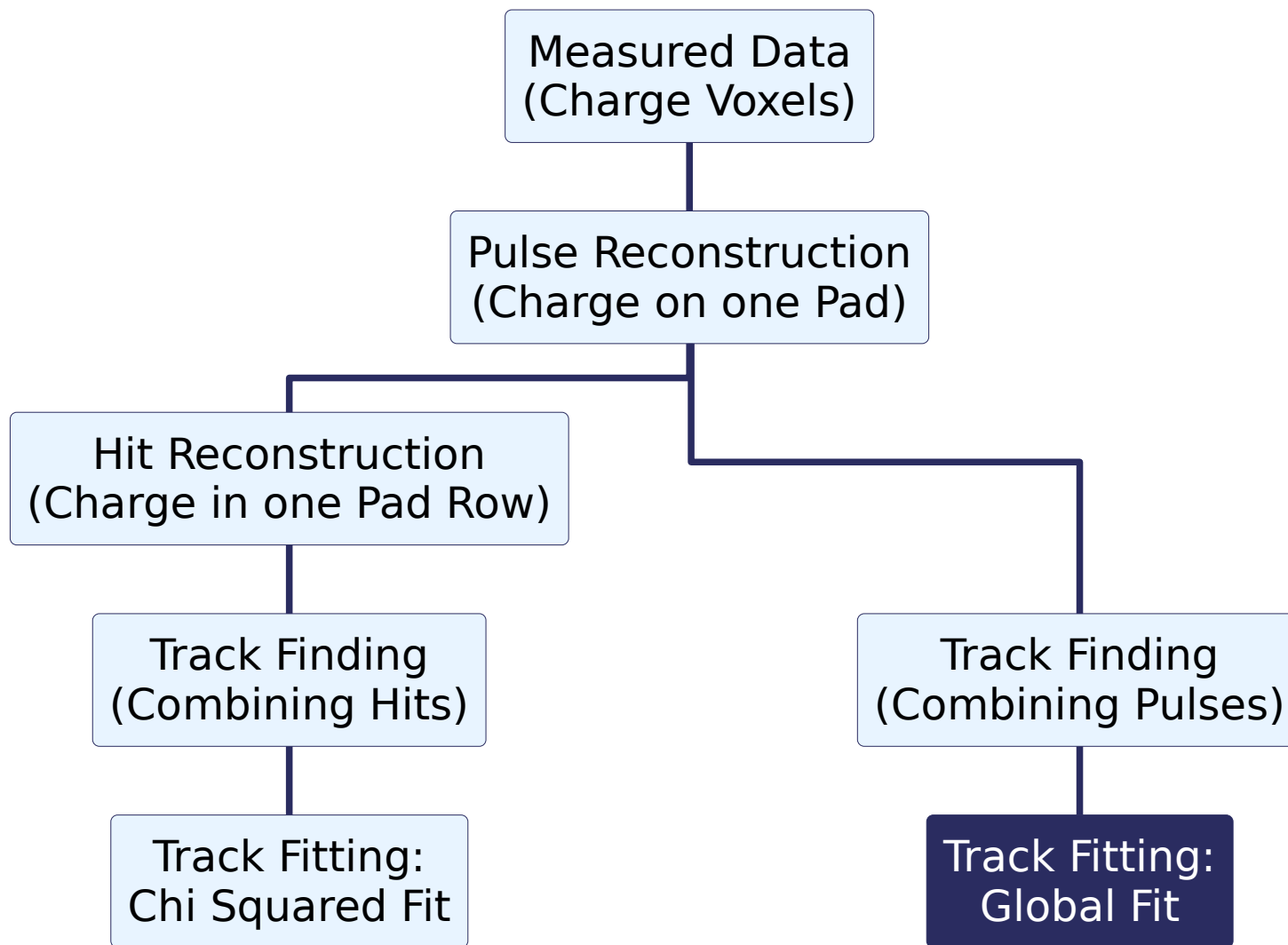
(minimized numerically)



Track Object

- Track Object
- Collection of constituents:
 - A vector (array) of Hits resp. Pulses belonging to the track
- Track parameters:
 - Intercept (where does it enter the sensitive volume)
 - Slope (angle)
 - Curvature
 - Center of Circle
- Errors of the track parameters
- Chi Squared of the track fit (estimate of the fit quality)
- Optional: Number of parameters, dE/dx ,

Global Fit



Maximum Likelihood Method

- A sample of n independent observations x_1, x_2, \dots, x_n
- Theoretical distribution known: $f(x|a)$, with \mathbf{a} : Parameter to be estimated
- Calculate the likelihood function:

$$L(\mathbf{a}|x) = f(x_1|\mathbf{a})f(x_2|\mathbf{a})\dots f(x_n|\mathbf{a})$$

This can be recognized as the probability for observing the sequence of values x_1, x_2, \dots, x_n

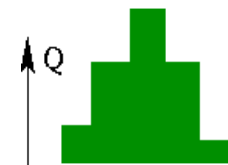
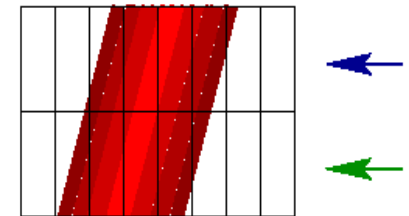
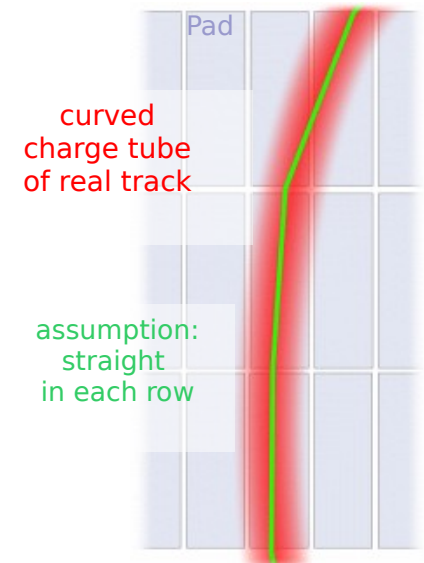
- Principle: this probability is a maximum for the observed values
So the parameter \mathbf{a} must be such, that \mathbf{L} is a maximum.
- So, \mathbf{a} can be found by solving: $\frac{dL}{da} = 0$

In practice: often easier to maximize the logarithm of \mathbf{L} : $\frac{d(\ln(L))}{da} = 0$ since: $\ln(y * z) = \ln(y) + \ln(z)$

this yields results which are equivalent to the above.

Global Fit

- Assumptions:
- For each row the track can be described by a straight line (height of a pad row much smaller than the radius of the curvature)
- Charge is Gaussian distributed along the track (this is a valid model for the charge deposition)
- Variations of the charge deposition are ignored: assume a constant charge deposition in a row



Global Fit

- Likelihood function describing charge deposition per pad:

$$L_i = p_i^{n_i}, \text{ with } n_i = \frac{N_i}{G} : \text{ number of primary } e^- , \text{ and } N_i : \text{ measured } e^-$$

G : gain factor

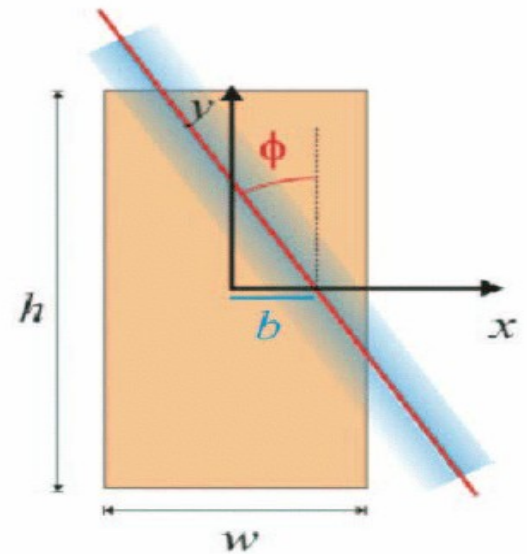
$$\text{and } p_i = \frac{Q_{\text{exp}}}{\sum_{\text{pads / row}} Q_{\text{exp}}} \quad (\text{probability function})$$

- Logarithm of product of likelihood functions of all pads:

$$\ln L = \sum_{\text{Rows}} \sum_{\text{Pad}} Q_{\text{measured}} \ln \left[\frac{Q_{\text{expected}}}{\sum_{\text{Row}} Q_{\text{expected}}} \right]$$

width of charge distribution included in fit function as free fitting parameter

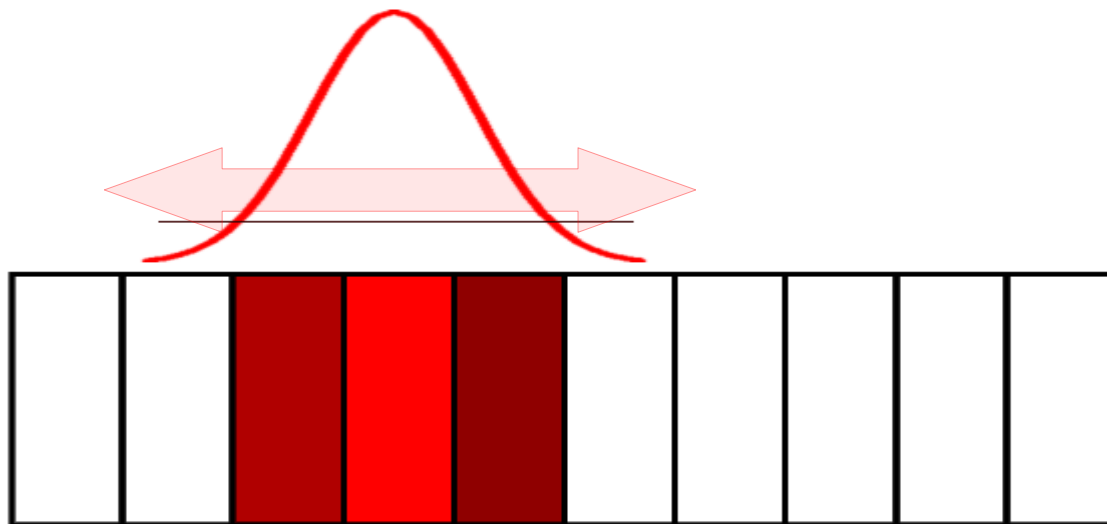
$$, \text{ with } Q_{\text{exp}} = \int_{-\frac{h}{2}}^{\frac{h}{2}} dy \int_{-\frac{w}{2}}^{\frac{w}{2}} dx \frac{1}{2\pi\sigma} e^{-\frac{[(x-X_0)\cos(\phi) + y\sin(\phi)]^2}{2\sigma^2}}$$



for details see: "TPC Performance in Magnetic Fields with GEM and Pad Readout", D. Karlen, P. Poffenberger, G. Rosenbaum, 2005

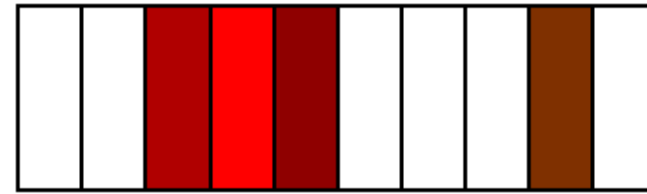
Hit Positions

- Hit is defined as the charge deposition in a row
- The X position of this charge deposition is needed for later resolution calculation, but the Global Fit in general has no hit reconstruction
- To get the position, do a Global Fit in just one line with the width, angle fixed to the result of the track fit:
this means moving a the charge distribution with fixed width and angle (depending on curvature) along the x axis until it fits best to the deposited charge in this row



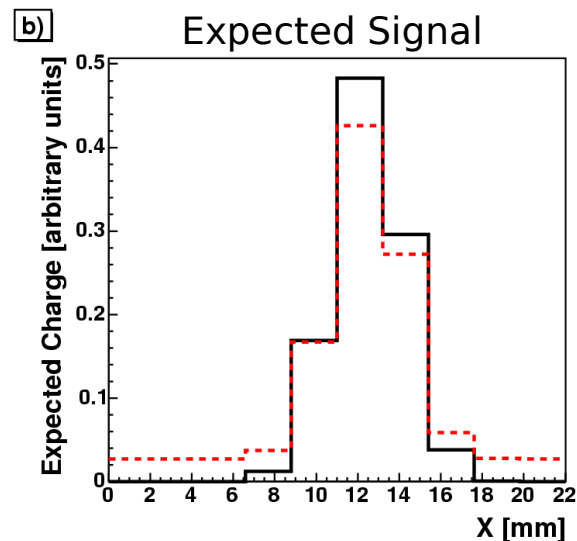
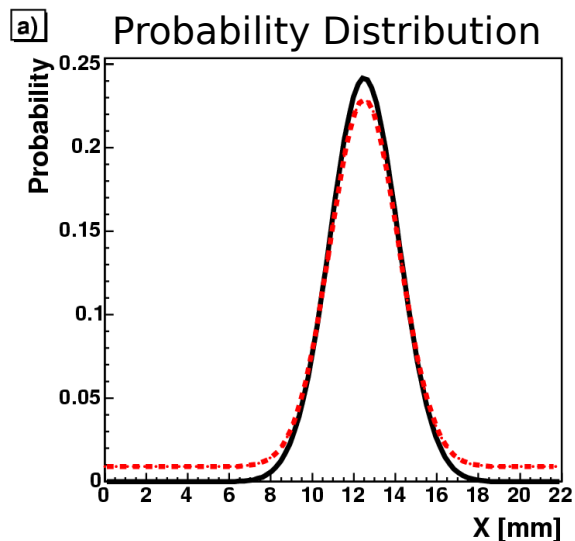
Global Fit

- What to do with noise Pulses?
They are not described by the theoretical distribution



- Solution: assign a higher probability for measuring a signal to all pads by introducing a constant offset: noise value N

$$p_i \rightarrow \frac{p_i + N}{1 + N \cdot n_{row}} \rightarrow \ln L = \sum_{Pad} Q_{measured} \ln \left[\left(\frac{Q_{expected}}{\sum_{Row} Q_{expected}} + N \right) / (1 + N) \right]$$



— without noise value
 ---- with noise value $N=0.01$

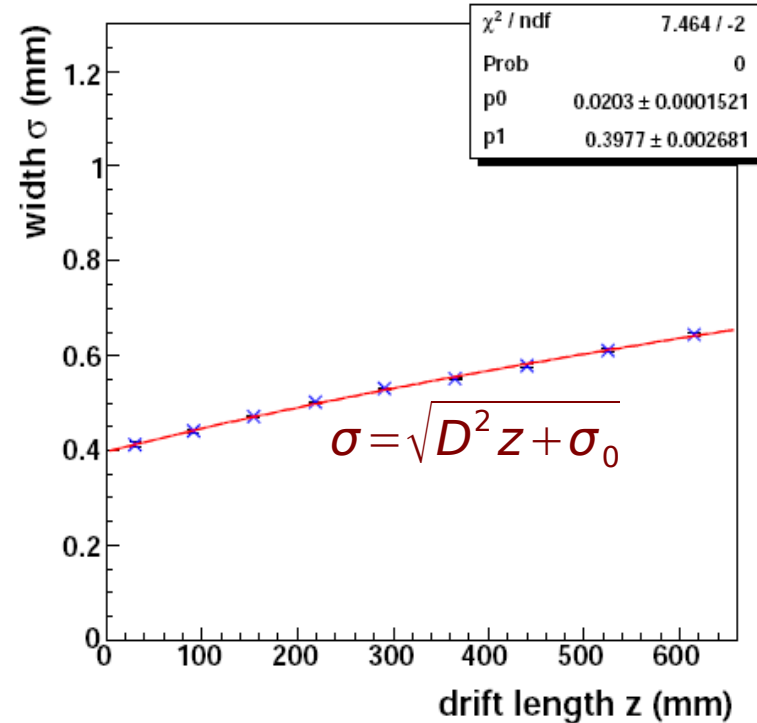
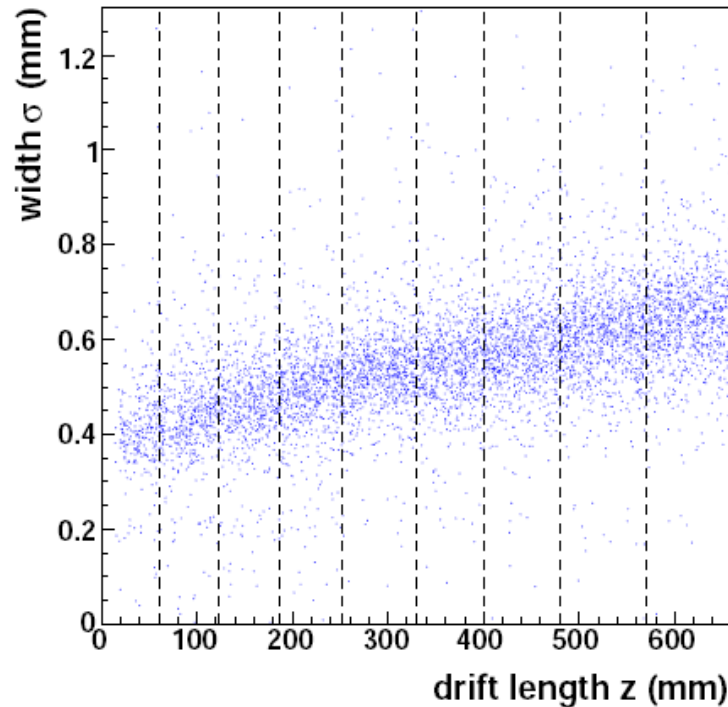
Example: pad row with 10 pads, pitch: 2.2mm

Track Object

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A vector (array) of Hits resp. Pulses belonging to the track
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 - Curvature
 - Center of Circle
 - Width of charge distribution
 - Errors of the track parameters
 - Optional: Number of parameters, dE/dx ,

Diffusion Parameters

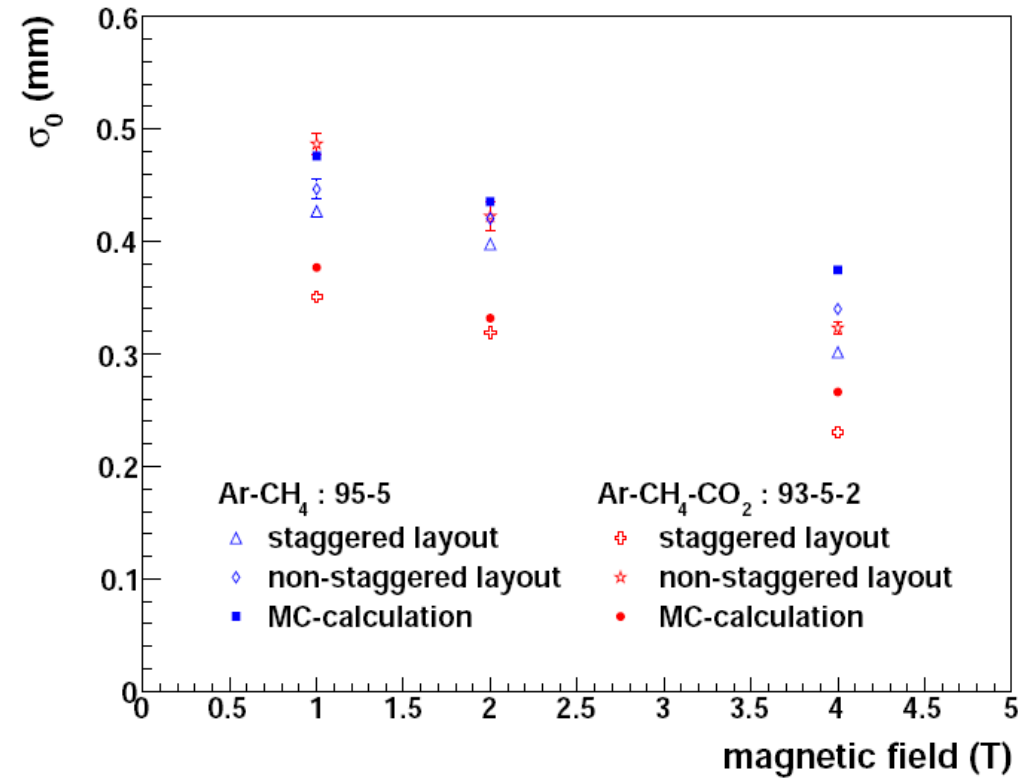
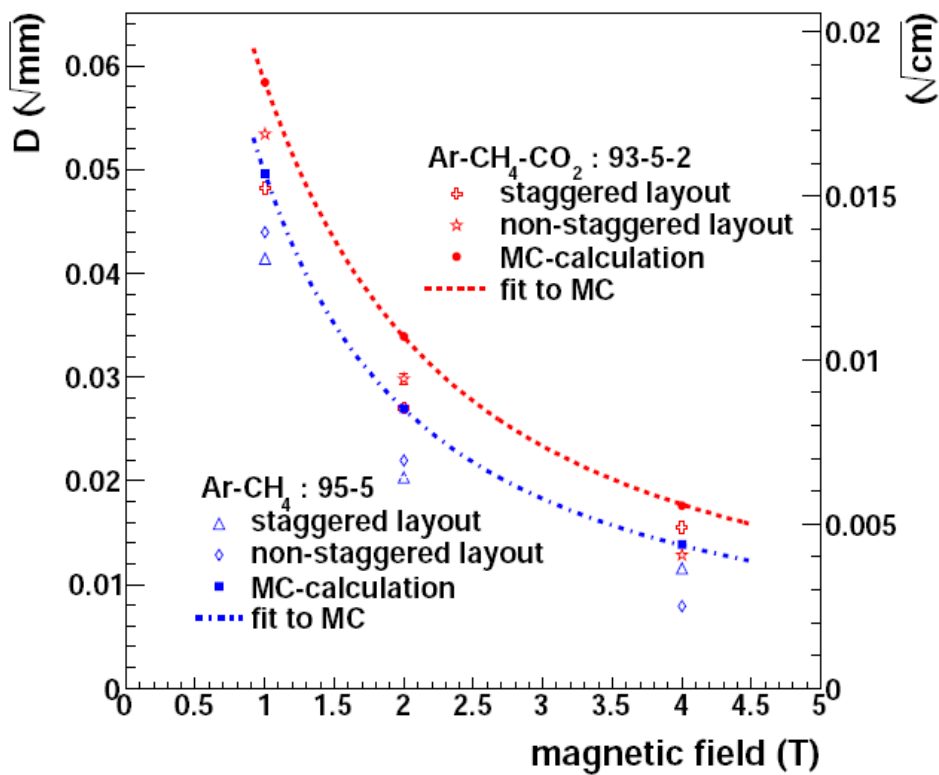
- From the Global Fit, also the diffusion and defocussing parameters of the setup can be determined



- Fit Gaussian to every interval and get mean values (with errors)
- Width of charge distribution can be described by: $\sigma = \sqrt{D^2 z + \sigma_0}$
- Fit this function with D and σ_0 as free parameters to the mean values of the intervals to get the parameter values

Diffusion Parameters

- Results from simulation compared to results from Global Fit results



- Results from Global Fit are in the right order of magnitude but underestimate the coefficients
Among other, possible explanation: wrong noise factor (1%),
further investigation planned

Remarks

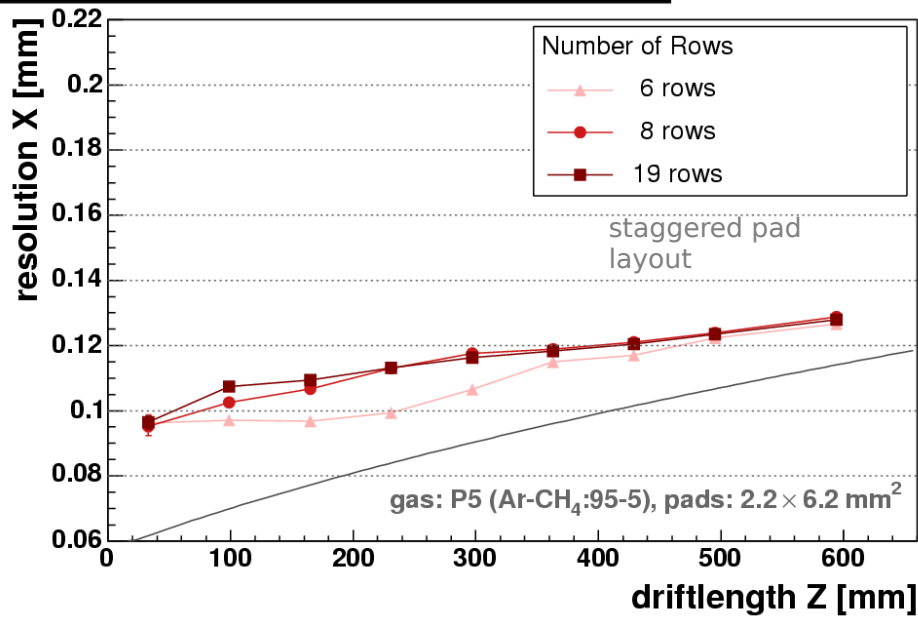
- Global Fit has the advantage that pad response effects are incorporated in the fit function
- Also, missing information (damaged pad) does not affect the fit too much since the term in the sum simply vanishes

$$\ln L = \sum_{Pad} Q_{measured} \ln \left[\frac{Q_{expected}}{\sum_{Row} Q_{expected}} \right]$$

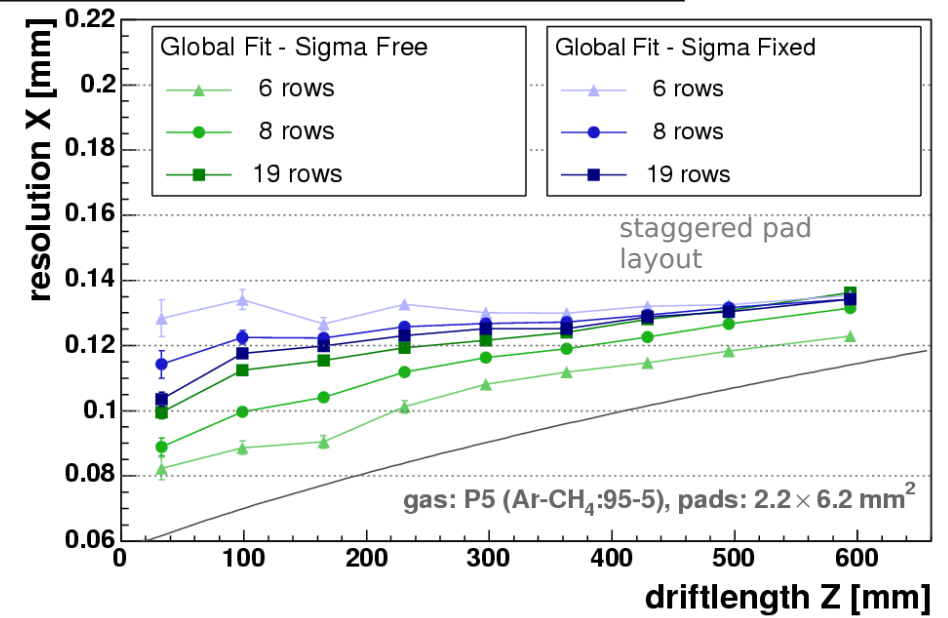
- Disadvantage: the fit is time consuming with many pad rows: for 6 pad rows Chi Squared Fit and Global Fit need approximately the same time, for 19 rows the Global Fit needs approximately three times longer than the Chi Squared Fit
- If not many pad rows are used, Global Fit can produce too good resolution results
- Width can be fixed during the fit (for a certain Z per row)
- Fit in YZ plane done with Chi Squared straight line fit

Comparison of Fit Methods

Point Resolution: MC, 4T, Chi Squared with PRC



Point Resolution: MC, 4T, Global Fit Method



- Chi Squared Method:
 - 6 rows in comparison too good
 - 8 rows already reasonable
 - 19 rows results show expected shape and are comparable with Global Fit results for 19 rows

- Global Fit with free σ :
 - 6 rows unreasonably good
 - 8 and 19 rows tend to more reasonable results
- Global Fit with fixed σ :
 - results conservative and scale with increasing number of rows
- Both flavors comparable at 19 rows

Comparison of Fit Methods

- “Robustness” of the fit methods:
influence of damaged pads
(dead channels) tested with
Monte Carlo simulation for
4T, P5 gas

